

液中AFMおよび接触過程の理論シミュレーション

Theoretical simulation of the contact mechanics
for AFM in liquid

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科学技術振興機構研究成果展開事業

【先端計測分析技術・機器開発】

「走査プローブ顕微鏡シミュレータ」



学振ナノプローブ167委員会 第67研究会
2012.7.17-18 物質材料研究機構(NIMS)

outline

1. はじめに

Introduction

2. SPM シミュレータの紹介

比較型シミュレータ, 他

Introduction of the SPM simulator

A solver for comparing experimental and simulation results, and others

3. 液中におけるカンチレバー振動

Vibration of cantilever in liquid

4. 水分子に媒介される探針-試料間力

Interactive force between the tip and the sample affected by solvent molecules

5. 接触問題

Viscoelastic contact problem

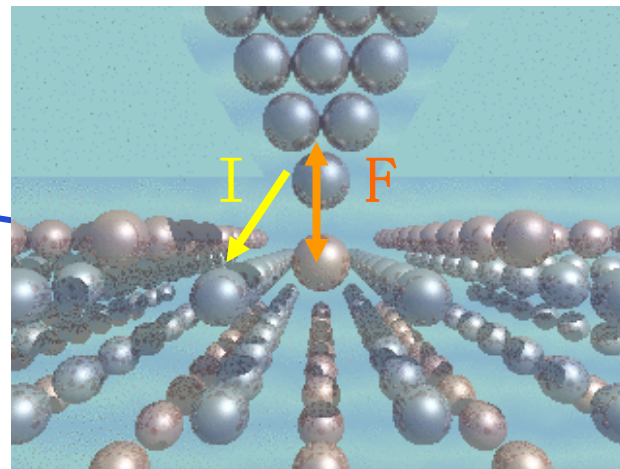
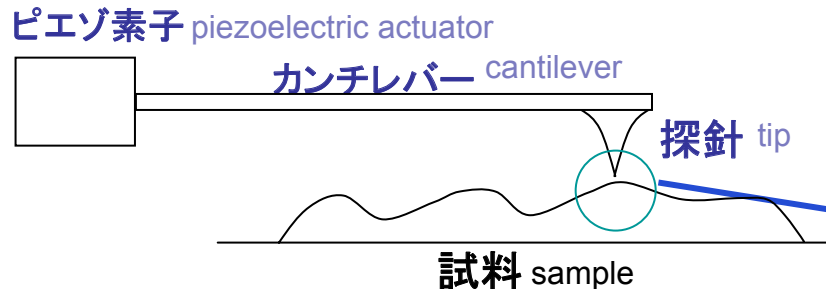
6. 終わりに

Concluding remarks

走査プローブ顕微鏡の理論

The theory of the scanning probe microscopy

STM/STS, AFM
KPFM, SNOM,....



What and how
Does SPM see the sample?

Why can the macro equipment obtain the information about each individual atom?

個々の原子レベルの情報が
マクロな装置でなぜ読み取れる？

ナノ構造の生成
と制御

Generation and control of the nanostructure

ミクロな力と変位？
揺らぎと温度効果
量子効果？
液中計測の機構？

The microscopic force and the displacement?
The fluctuations and the thermal effects
The quantum effect?
The observation mechanism in liquid?

量子現象の観察と
機能発現

Observation of quantum phenomena and emergency of functions

探針の原子構造・
原子種の効果？

The effect of the structure and the atomic species of the tip?

SPMシミュレーター

SPM simulator

科学技術振興機構研究成果展開事業
 【先端計測分析技術・機器開発】
 「走査プローブ顕微鏡シミュレーター」2004~2007, 2009~2011

1. Rapid AFM simulator for tip/sample/image

1A. Geometrical Mutual AFM Simulator (GeoAFM)
 Rapid image estimation by the geometrical method

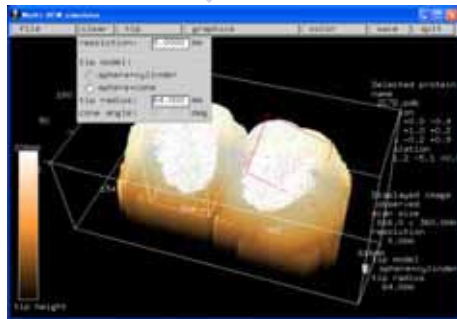
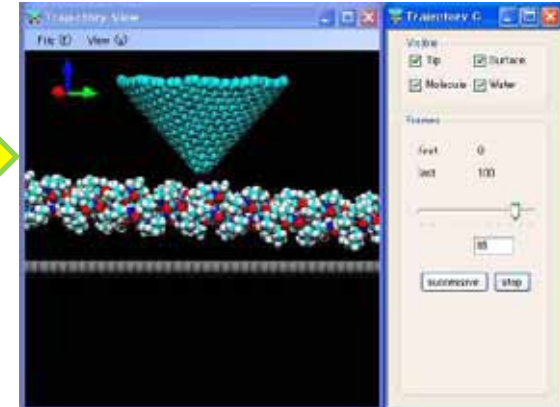
1B. Finite Element Method AFM simulator (FemAFM)
 Complement GeoAFM by numerical calculations of finite element method

3. AFM image simulator for atoms/molecules/nanostructures

3A. Geometry Optimizing AFM Image Simulator
 (classical force field method, Molecular Mechanics)

3B. Molecular Dynamics AFM Image Simulator
 (the classical molecular dynamics)

(古典分子動力学法)



2. Soft Material Liquid AFM Simulator (LiqAFM)

Oscillation analysis of cantilever in liquid, AFM analysis of the visco-elastic sample, High-speed mode AFM analysis, Analysis of the multiple-frequency excitation

Numerical calculation of the cantilever's elastic deformation and the fluid resistance using the mesh

流体抗力のメッシュによる数値計算

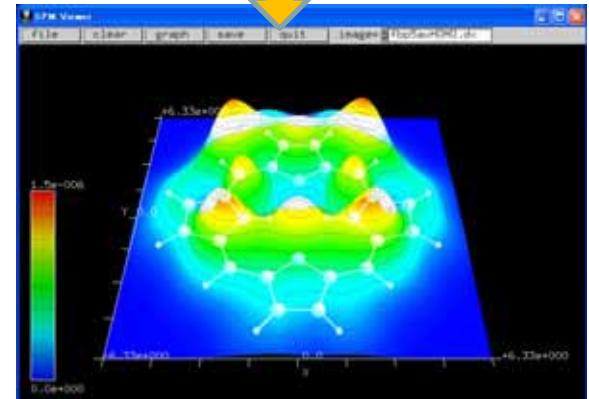
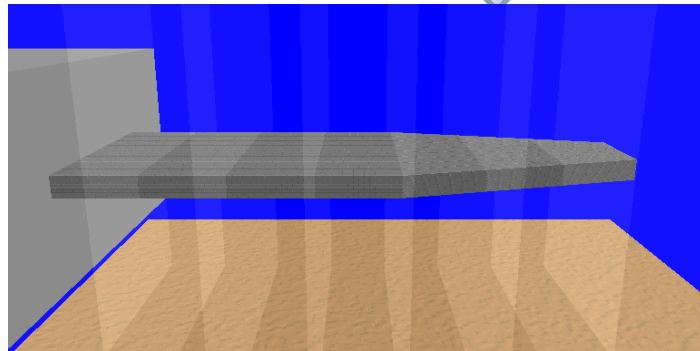
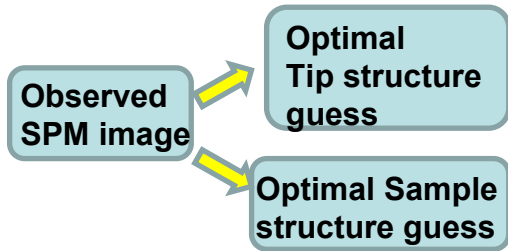
4. 量子論的

4. Quantum mechanical AFM/STM/KPFM Simulator

High-precision image estimation by Quantum mechanics

DFTB method, PR-DFTB method

DFTB法、PR-DFTB法



"Observation-simulation" comparison type simulator

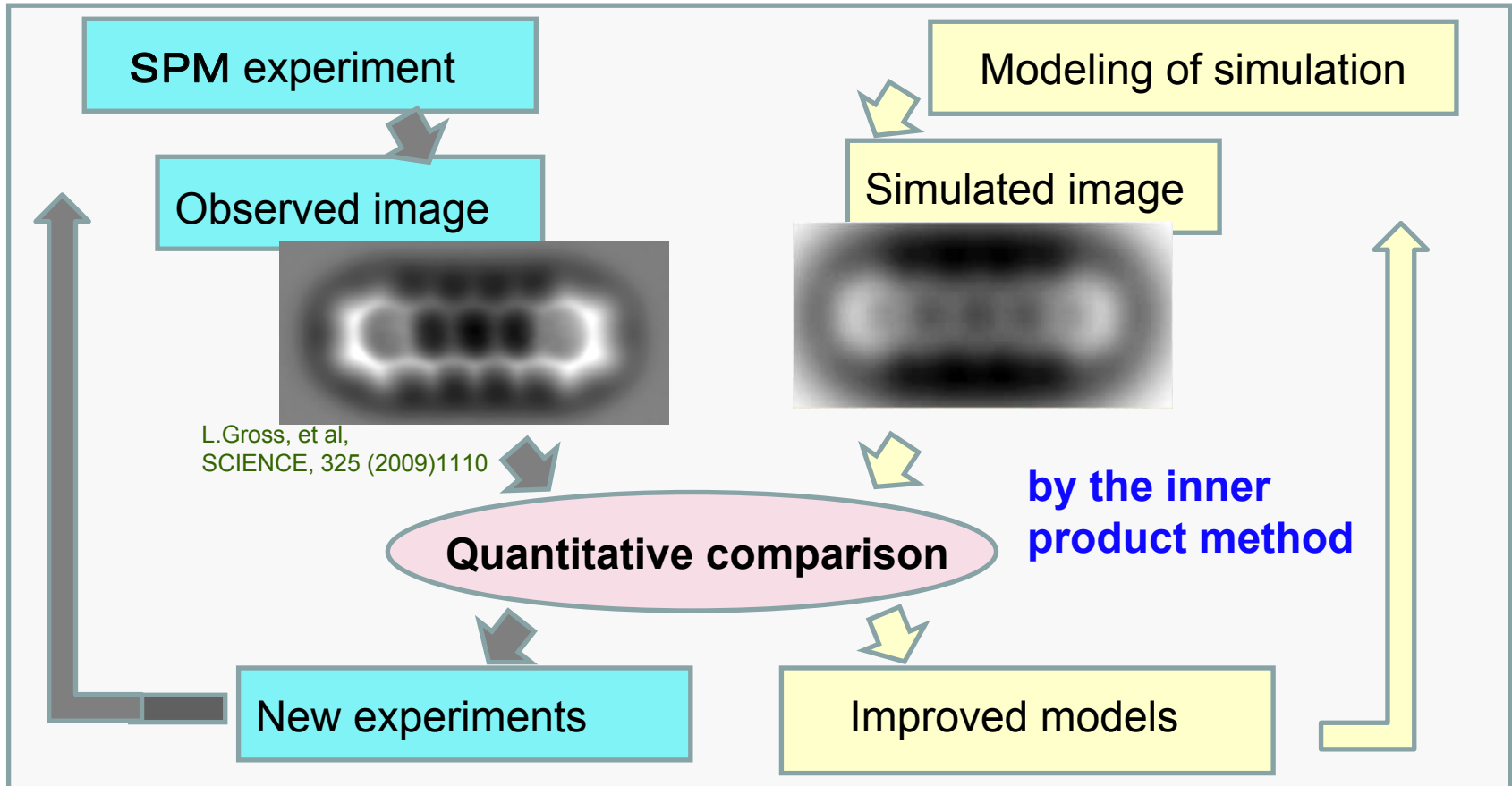
Inverse problem!

Observed
SPM image



Optimal tip structure guess

Optimal sample structure guess

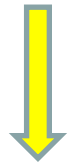


**Model reconstruction
with optimization/neural network approach**

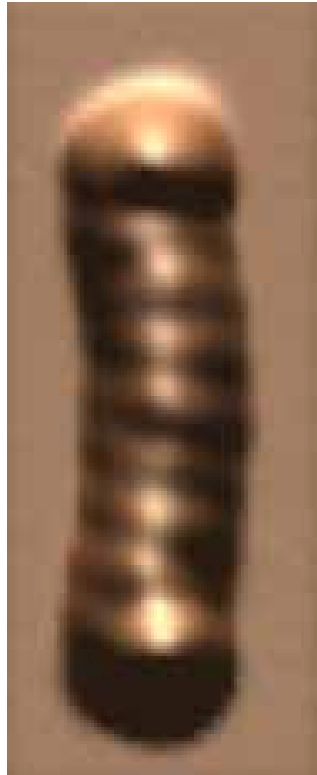
AFM images by the geometrical method and the force method

3. AFM image simulator for atoms/molecules/nanostructures

1. Rapid AFM simulator for tip-sample-image



Calculated by
Interaction
force



a few hours(WS)

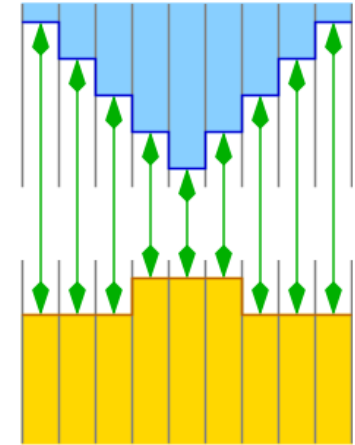
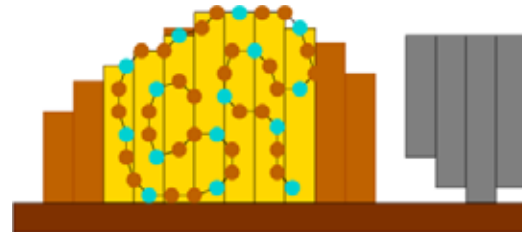


Calculated by
Geometrical
condition



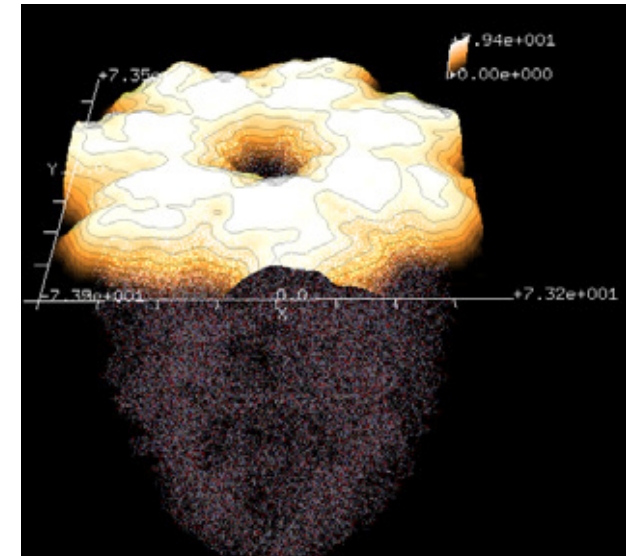
less than 1 sec(PC)

Using only geometrical
condition



The case of
collagen

The case of GroEL



Applications of the AFM simulator

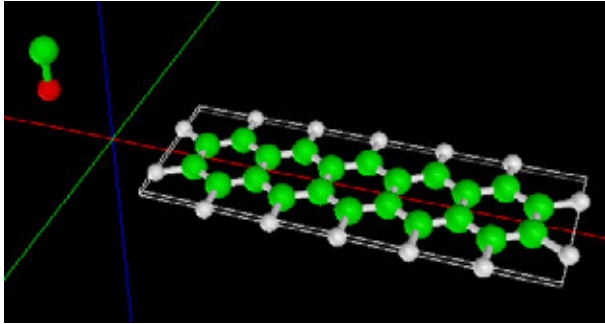
Using classical force field,

3. AFM image simulator
for atoms/molecules/
nanostructures

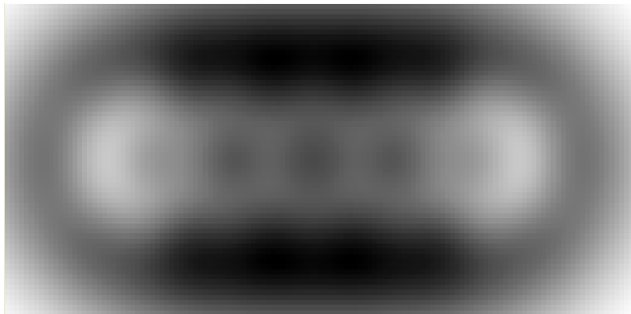
$$\Delta f = rf_0 = -\frac{f_0}{2kA\pi} \int_0^{2\pi} F(A \cos \theta + L) \cos \theta d\theta$$

AFM image of pentacene by a CO tip

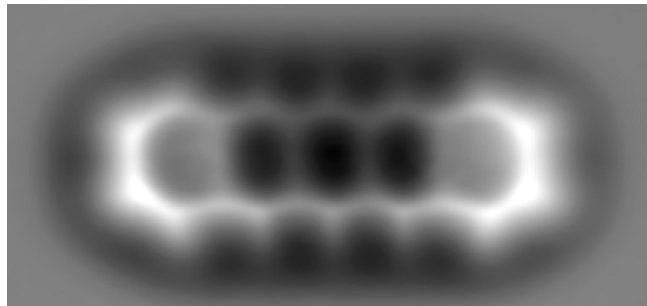
- fixed sample structure
- constant height
- calculation time
20 min with PC



simulation



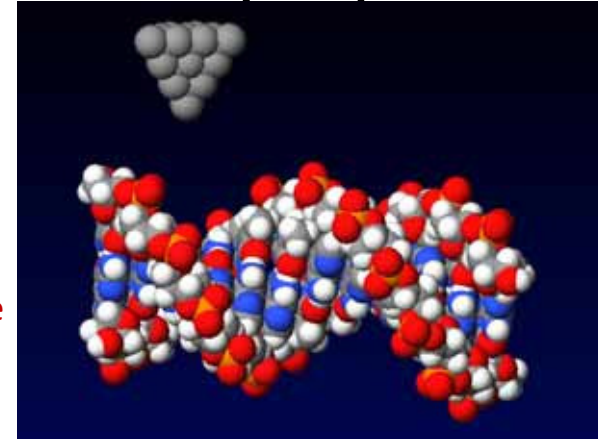
experiment



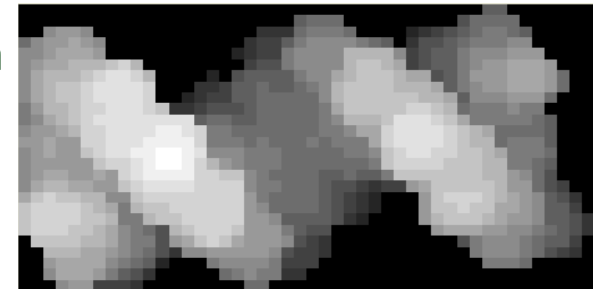
L.Gross, F.Mohn,
N.Moll, P.Liljeroth,
G.Meyer,
SCIENCE, 325
(2009)1110

AFM image of DNA by C tip

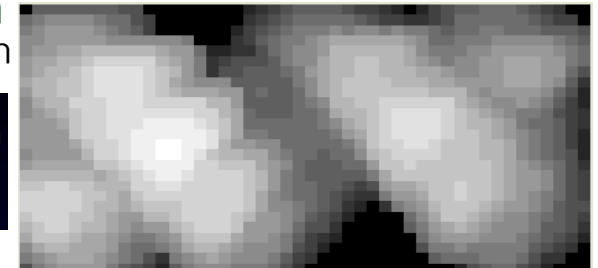
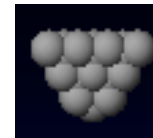
- DNA structure fixed
- constant frequency
- calculation time
3 hours with PC



simulation
Tip C 1 atom



simulation
Tip C 29 atom



Non-Contact AFM image of methyl group on Si(100)/H

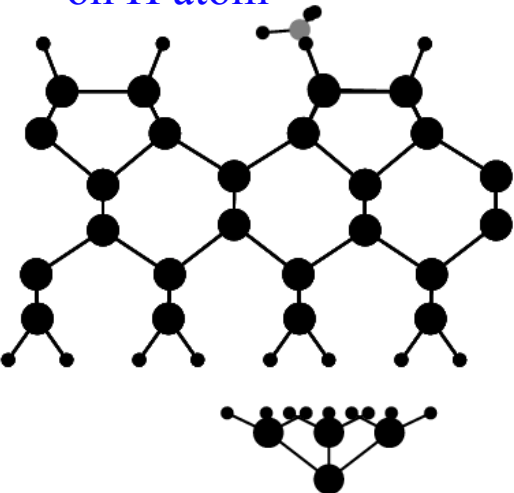
A. Masago et al, Jpn. J. Appl. Phys., 48, 025506 (2009)

DFTB calculations



$$\Delta f = -\frac{f_0}{2kA\pi} \int_0^{2\pi} F(A\cos\theta + L) \cos\theta d\theta$$

on H atom

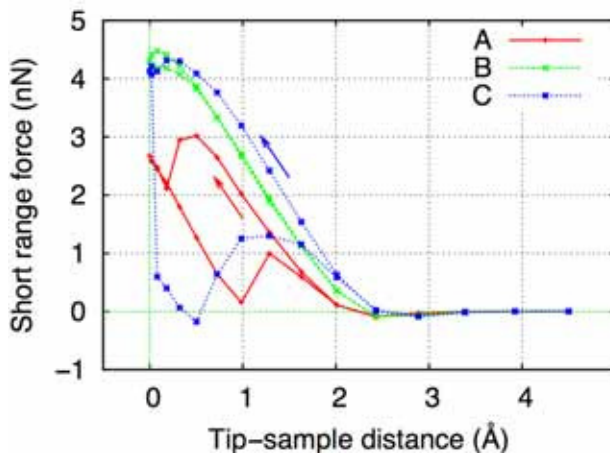
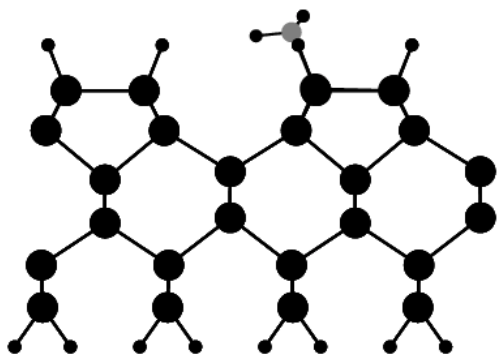


Frequency shift image

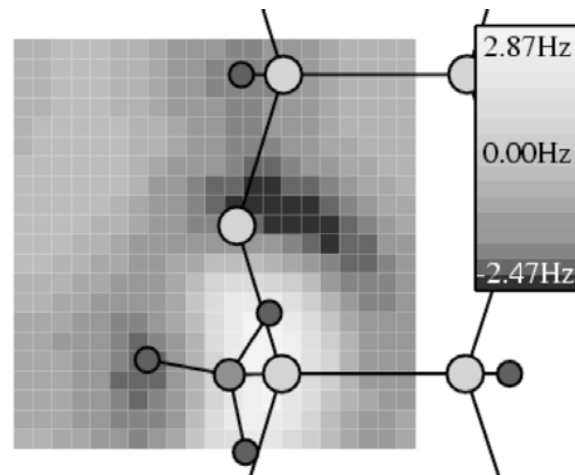
Constant height

$$h = \frac{1}{\pi\omega_0} \int_0^{2\pi} \gamma(A\cos\theta + L) \sin^2\theta d\theta + \frac{1}{2kA\pi} \int_0^{2\pi} F(A\cos\theta + L) \sin\theta d\theta$$

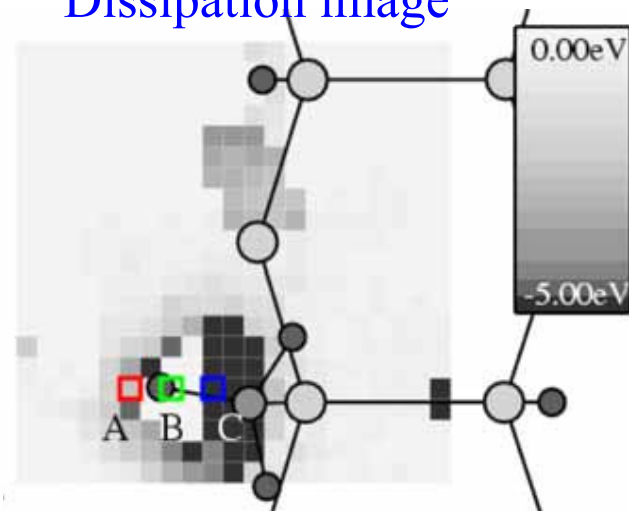
on methyl



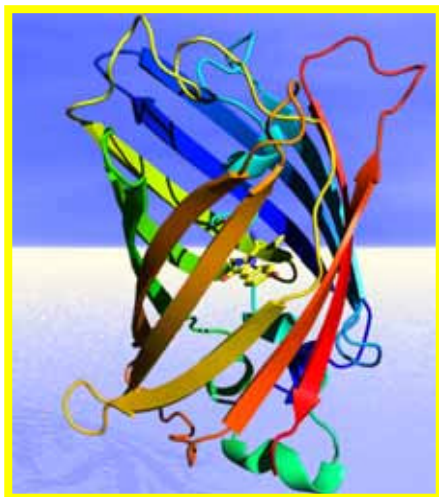
4. Quantum mechanical AFM/STM/KPFM simulator



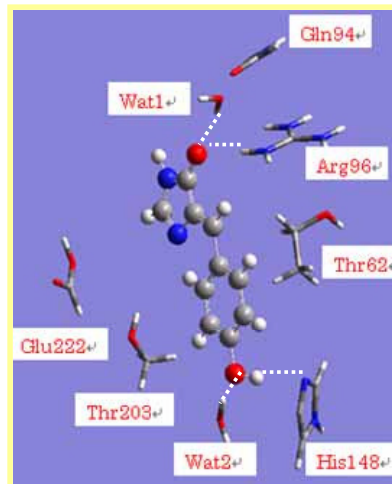
Dissipation image



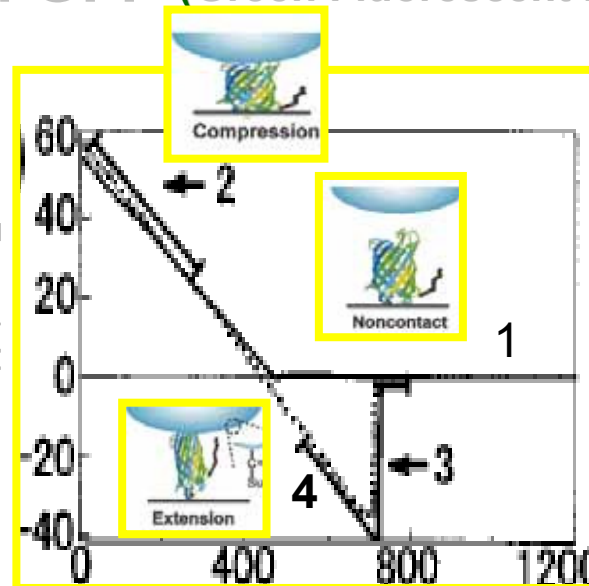
Nano-mechanical experiment on GFP (Green Fluorescent Protein)



Structure by X-ray



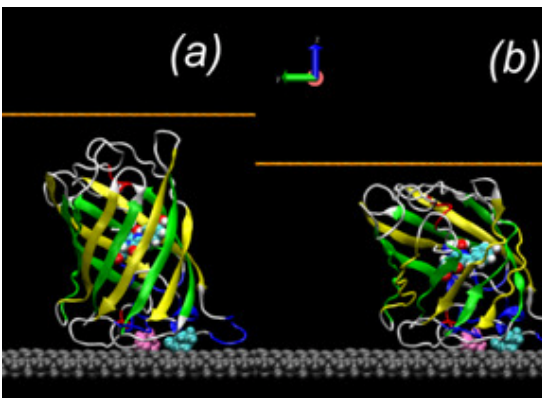
Cromophore



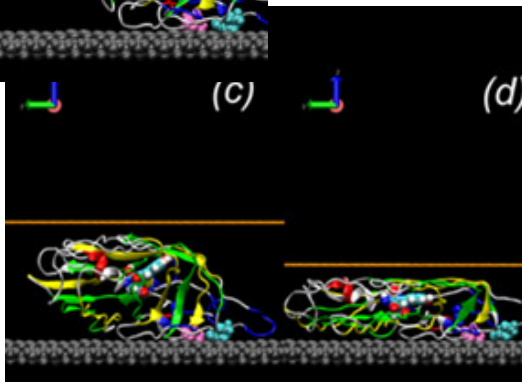
Remarkable quenching of fluorescence

Tip height (nm)

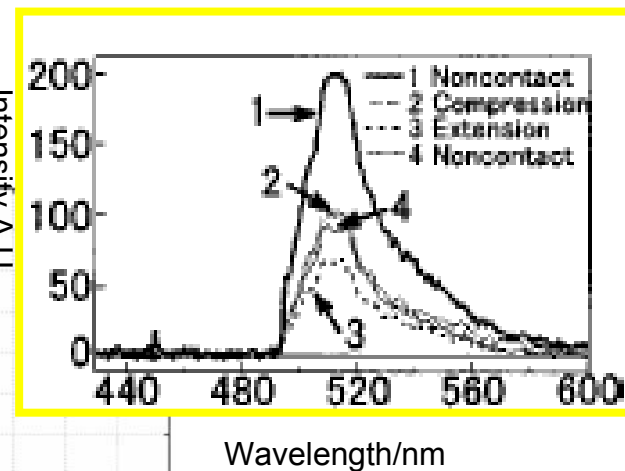
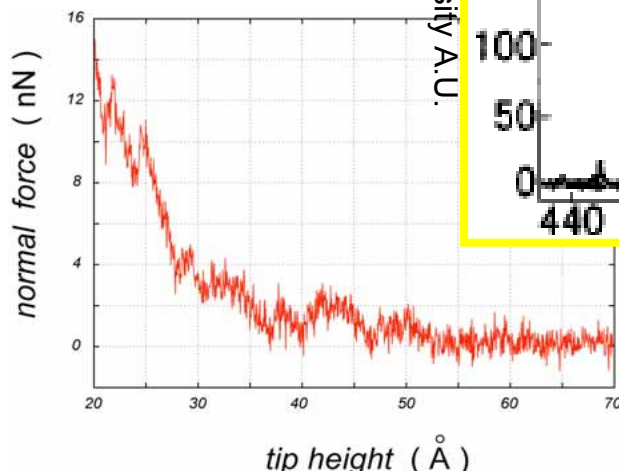
T. Kodama, H.Ohtani and A.Ikai, *Appl. Phys. Lett.* 86 043901(2005)



MD simulation of compression with a flat tip



Force-distance curve

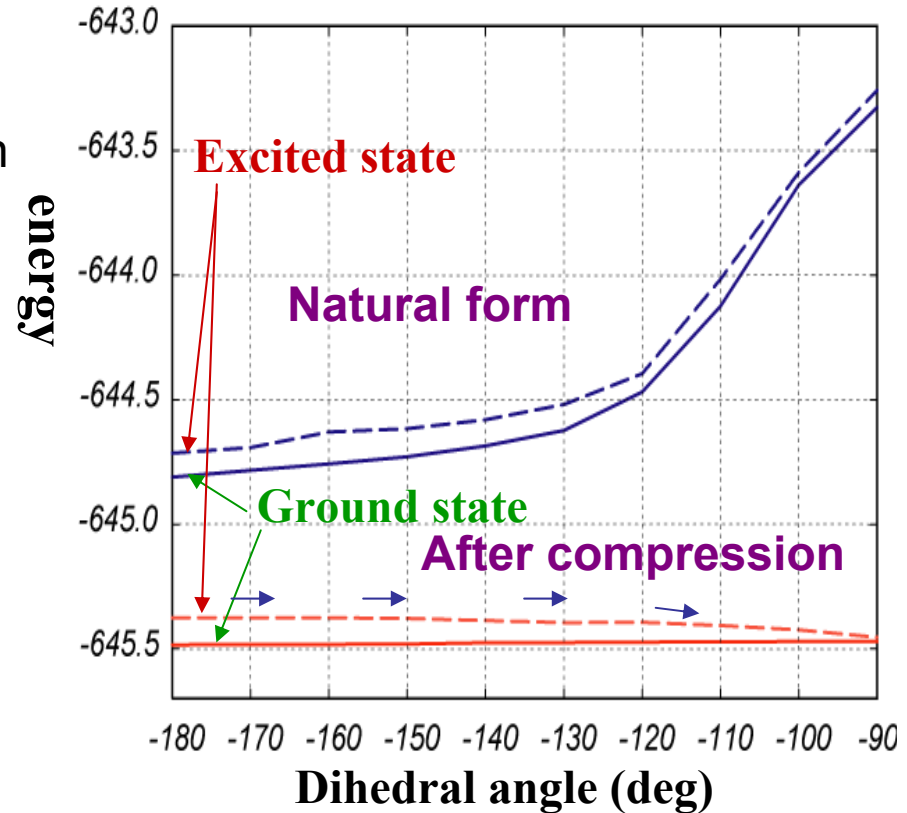
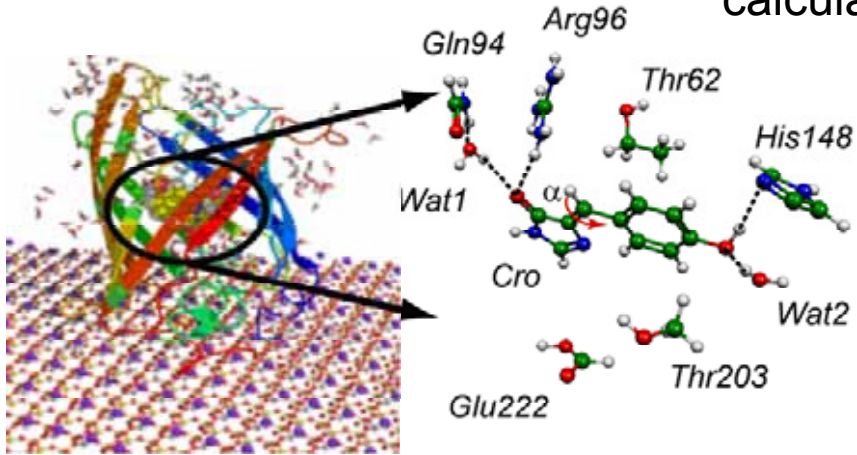


Q.Gao, et al,
Jpn.J.
Appl.Phys., 45
(2006) L929

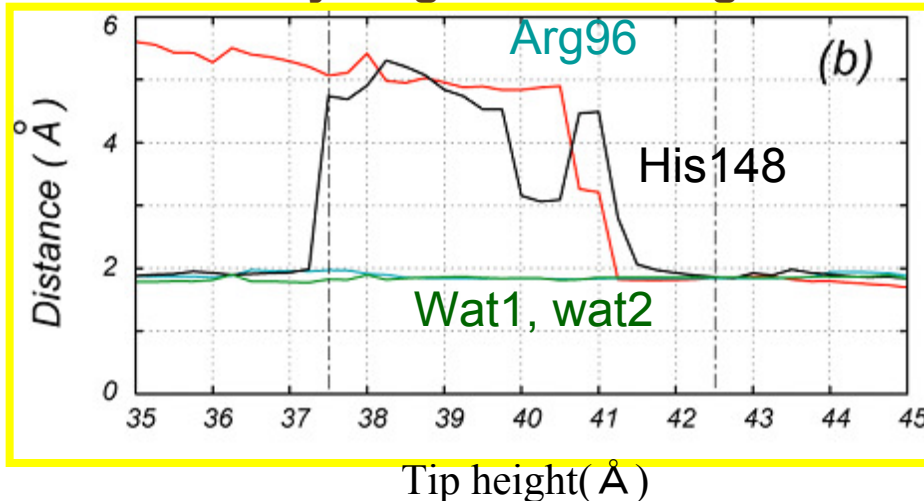
Mechanism of suppression of light emission

-Simulation of nano-mechanical experiments

T. Kodama, H. Ohtani and A. Ikai, Appl. Phys. Lett. 86 043901(2005)



Hydrogen bond length

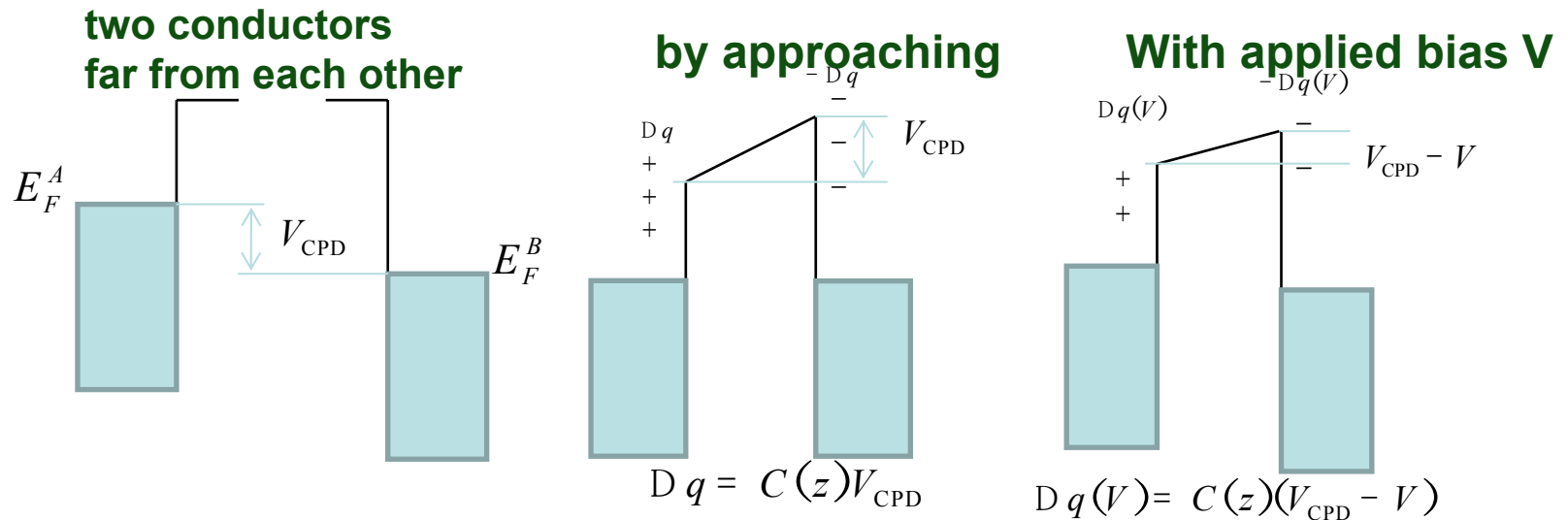


On the compression, rotation barrier disappears

Non-radiative processes take place

Emission suppressed

Theory and simulation of Kelvin Probe Force Microscopy(KPFM)

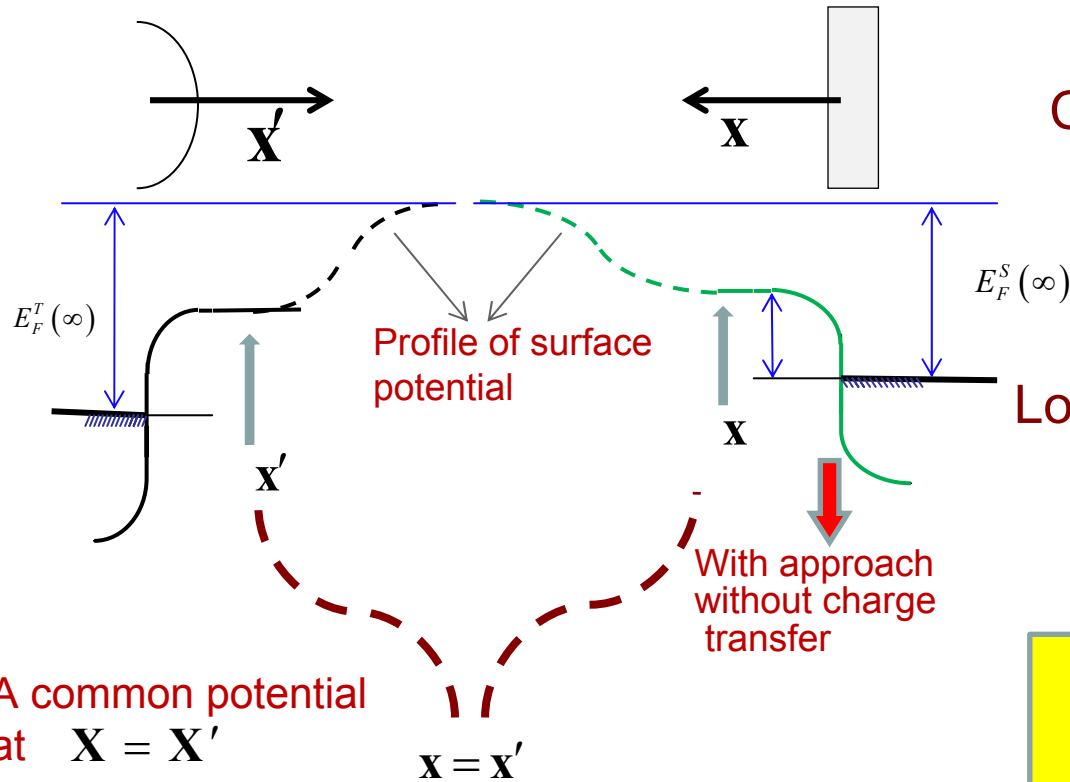


Contact potential difference V_{CPD} is a global(averaged) quantity, but in KPFM experiment, it depends on the tip position ?!

How is the local contact potential V_{LCPD} difference explained?

$$F = -\frac{1}{2} \frac{\partial C(z)}{\partial z} (V_{CPD} - V)^2$$

What is the Local Contact Potential Difference V_{LCPD} ?



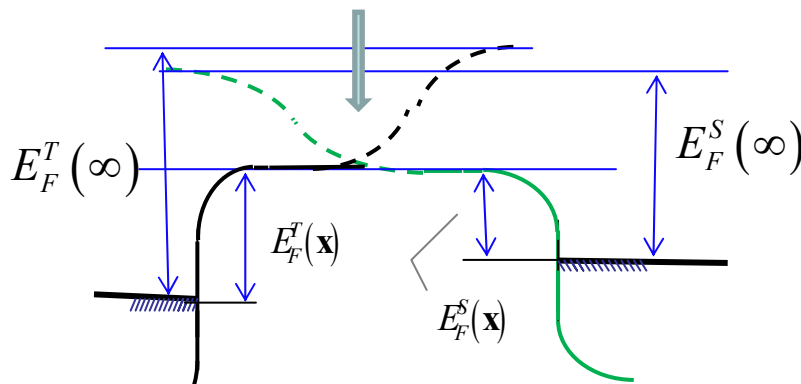
Contact Potential difference

$$V_{\text{CPD}} = E_F^S(\infty) - E_F^T(\infty)$$



Local Contact Potential Difference

$$V_{\text{LCPD}}(\mathbf{x}) = E_F^S(\mathbf{x}) - E_F^T(\mathbf{x})$$



$$V_{\text{LCPD}}(\mathbf{x}) = E_F^S(\mathbf{x}) - E_F^T(\mathbf{x})$$

The local contact potential difference

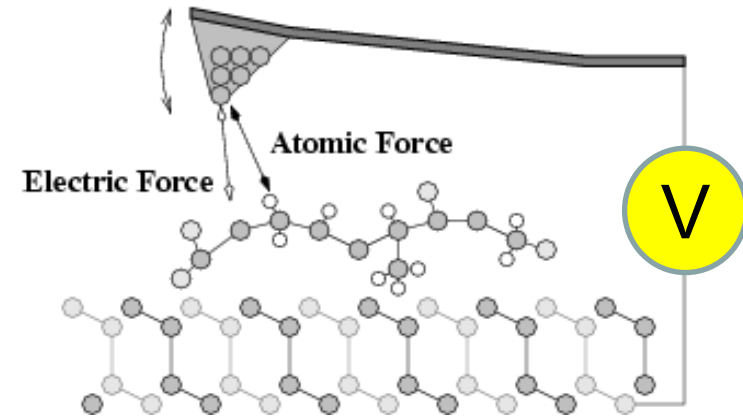
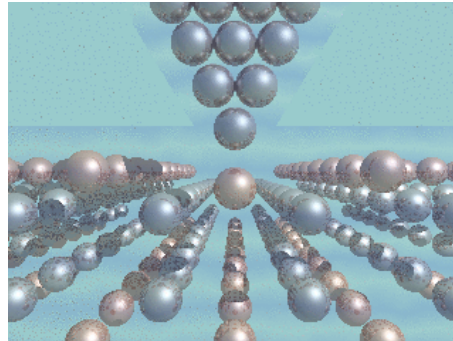
$V_{\text{LCPD}}(\mathbf{x})$ is determined by nano-scale surface potential governed by local charge distribution, but approach of the tip and the sample modifies the local charge distribution.

Simulation of KPFM Images

What is the “Local Contact Potential Difference” ?

Partitioned real space
DFT based tight binding method

**PR-DFTB method
+perturbation**



For a given charge transfer Dq

solve electronic state of Tip with
potential field of Sample

solve electronic state of Sample
with potential field of Tip

Electronic state charge
 $\{\varphi_i^T\}, \rho_T(\mathbf{r})$

$\{\varphi_i^S\}, \rho_S(\mathbf{r})$

Fermi level offset , i.e., applied bias and force
are determined for this charge transfer, then

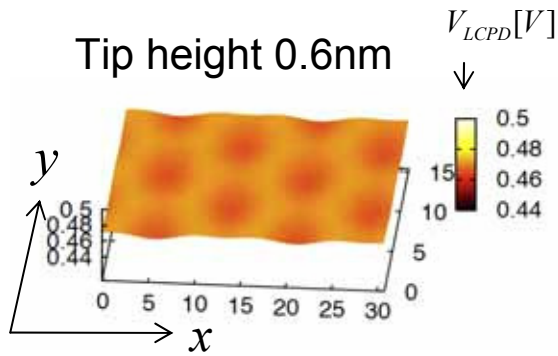
$$E_F^A(Dq) - E_F^B(Dq) = e(V(Dq) - V_{LCPD})$$

V_{LCPD} , local contact
Potential difference
determined

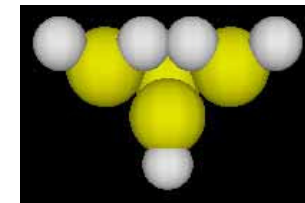
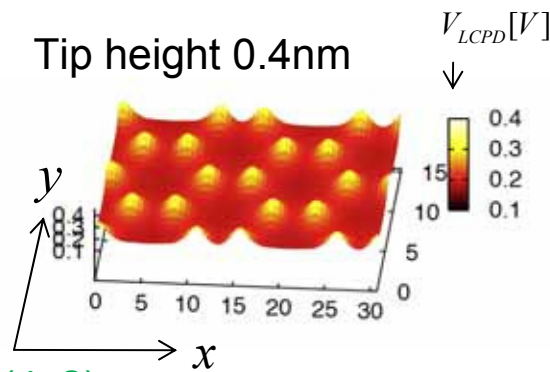
perturbation for
the chemical force

KPFM image of Si(001)-c(4x2)

-image of local contact potential difference-
effect of embedded impurity atoms

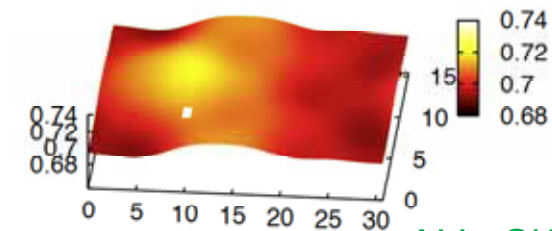
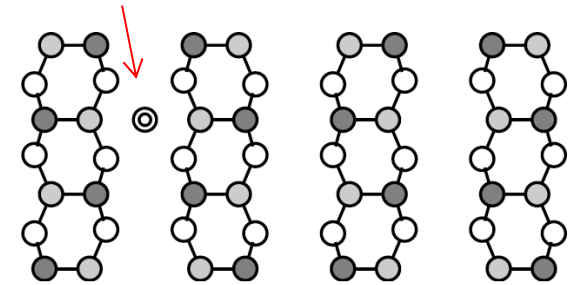


Si(100)c(4x2)

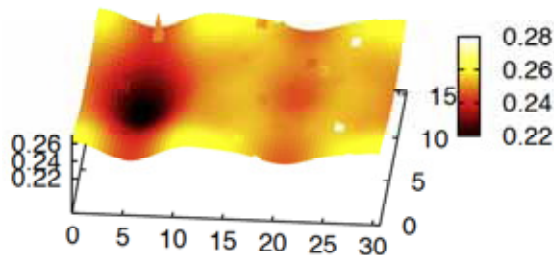
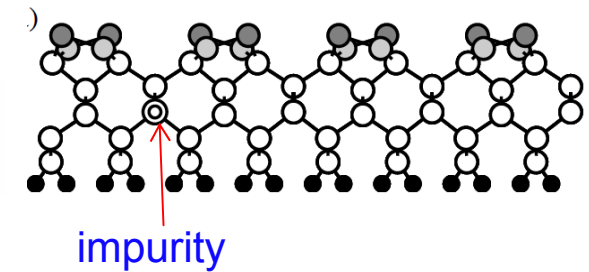
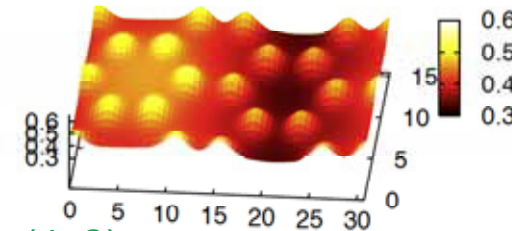


Si₄H₉ tip

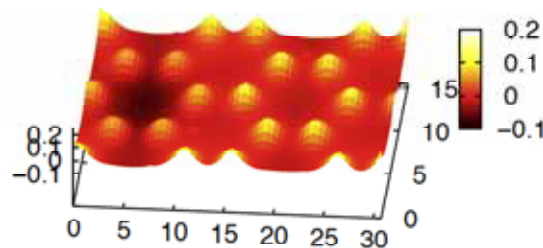
impurity



Al in Si(100)c(4x2)



P in Si(100)c(4x2)



液中ncAFMの理論シミュレーション

2. 液中ソフト材料AFMシミュレータ

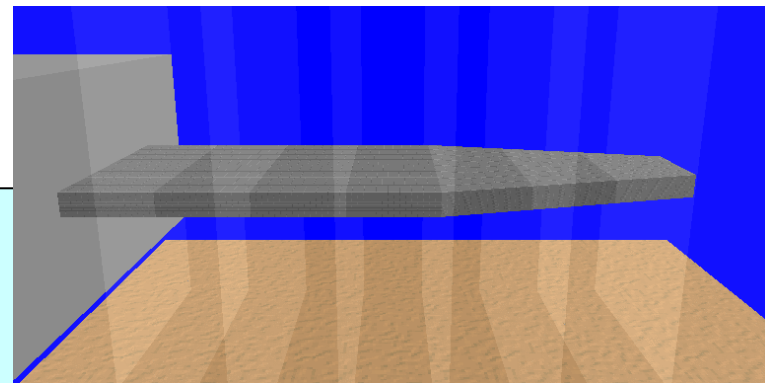
非線形
多モード
励振

液中における
弾性体振動

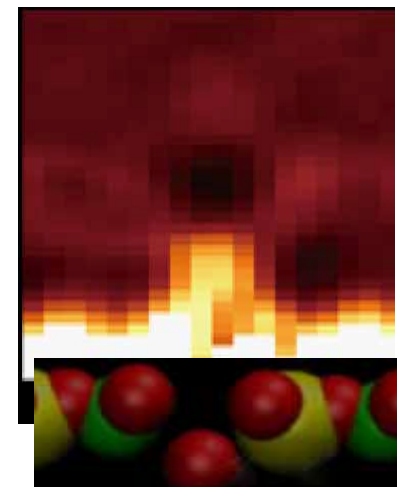
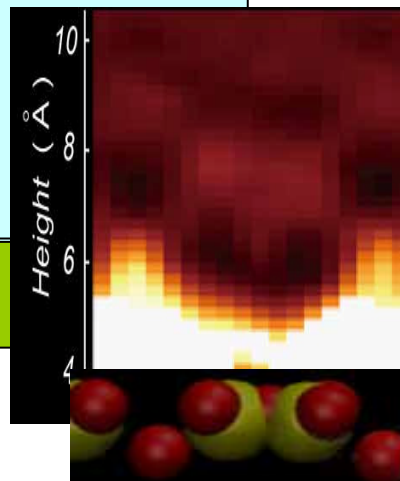
凝着

液体に媒介される力
3DRISM,
MD

ソフト材料の
粘弾性モデル

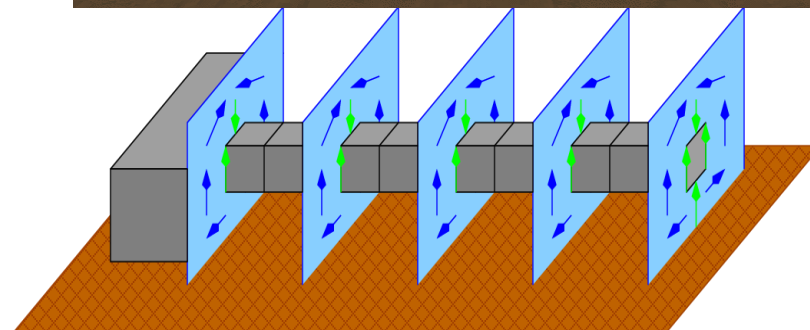
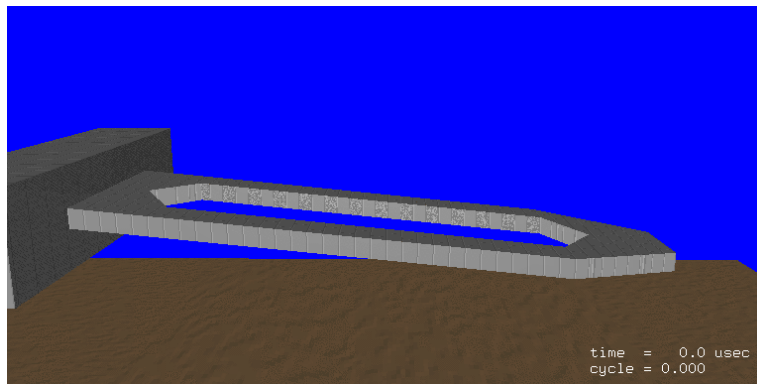


3. 原子分子ナノ構造AFM像シミュレータ



液中カンチレバー振動の解析理論

- 1) 共鳴曲線は？
- 2) 非線形効果は？
- 3) 基盤からの高さの影響？
- 4) 探針の受ける力の効果？



カンチレバー：
一方向に長い構造

$$\rho S(z) \frac{\partial^2}{\partial t^2} h(z) = - \frac{\partial^2}{\partial z^2} EI(z) \frac{\partial^2}{\partial z^2} h(z) + F^{\text{liq}}(z)$$

h ; カンチレバーの高さ

液体からの力

E ; ヤング率 modulus

I ; 断面の幾何学的能率

液体：
各断面で2次元の非圧縮流体

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = -\nabla P + \frac{1}{\text{Re}} \Delta \mathbf{v}$$

Navier-Stokes 方程式

Re ; レイノルズ数

Method for fluid dynamics on 2D

Flow function $\Psi \implies v_x = +\frac{\partial \Psi}{\partial y} \quad v_y = -\frac{\partial \Psi}{\partial x}$ **Velocity component of fluid**

vorticity $\omega \implies \omega = \partial_x v_y - \partial_y v_x \implies \frac{\partial^2 \Psi}{\partial x^2} + \frac{\partial^2 \Psi}{\partial y^2} = -\omega$

From Navier-Stokes eq.

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = -\nabla P + \frac{1}{\text{Re}} \Delta \mathbf{v}$$

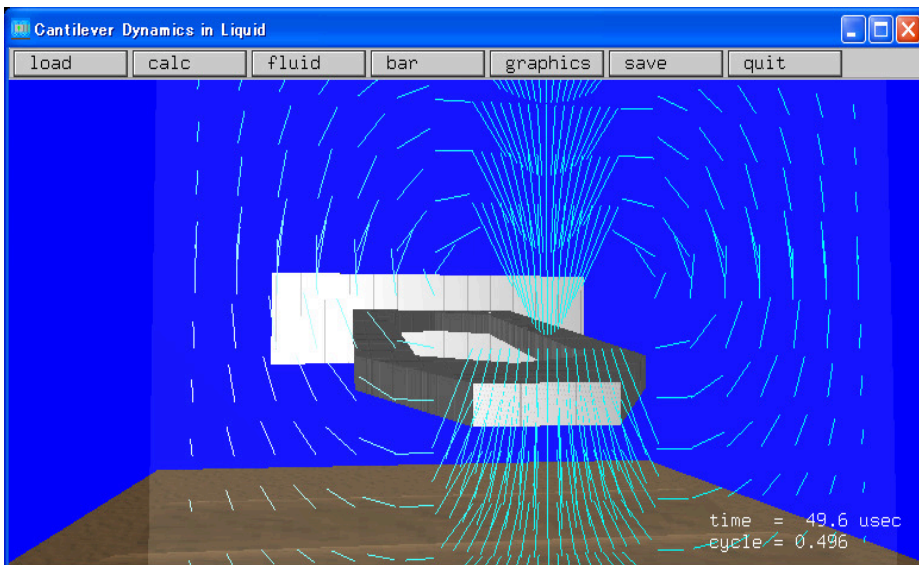
$$\frac{\partial \omega}{\partial t} = \left[\frac{\partial \Psi}{\partial x} \frac{\partial \omega}{\partial y} - \frac{\partial \Psi}{\partial y} \frac{\partial \omega}{\partial x} \right] + \frac{1}{\text{Re}} \left[\frac{\partial^2 \omega}{\partial x^2} + \frac{\partial^2 \omega}{\partial y^2} \right]$$

negligible

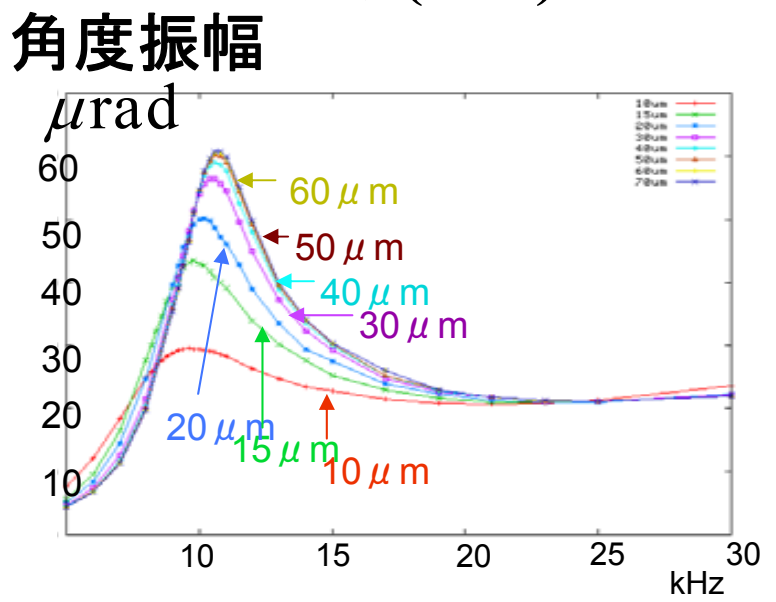
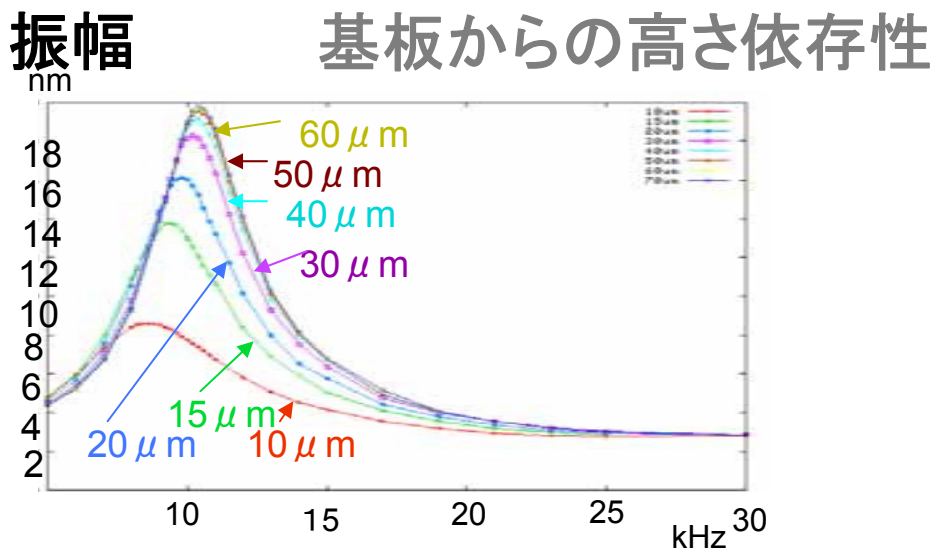
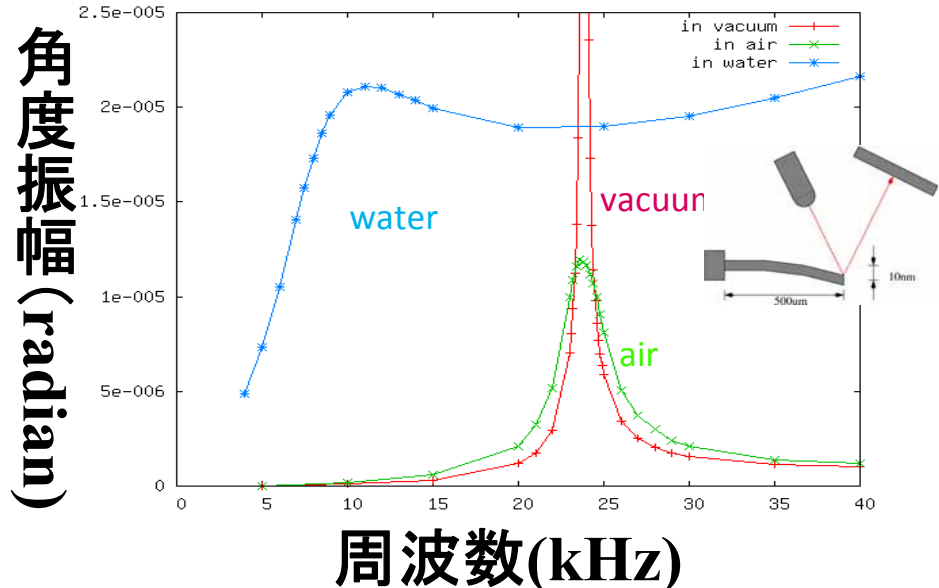
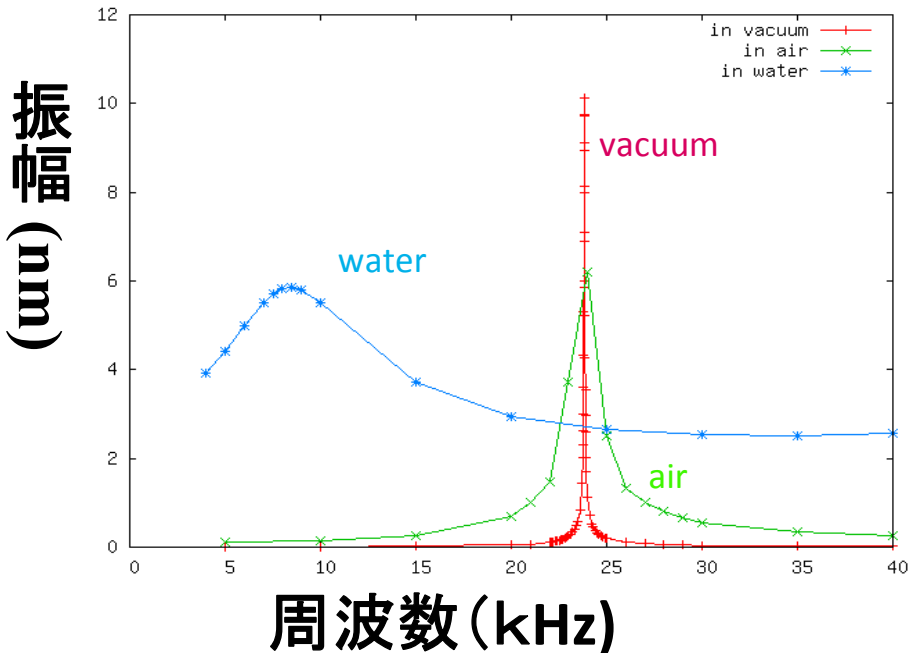
Closed equation of ω
solved by FEM

Force felt by cantilever is
given by

$$F_s = \oint \left(P + \frac{\omega}{\text{Re}} \right) dl$$



水中のSi矩形薄板カンチレバーの共鳴曲線

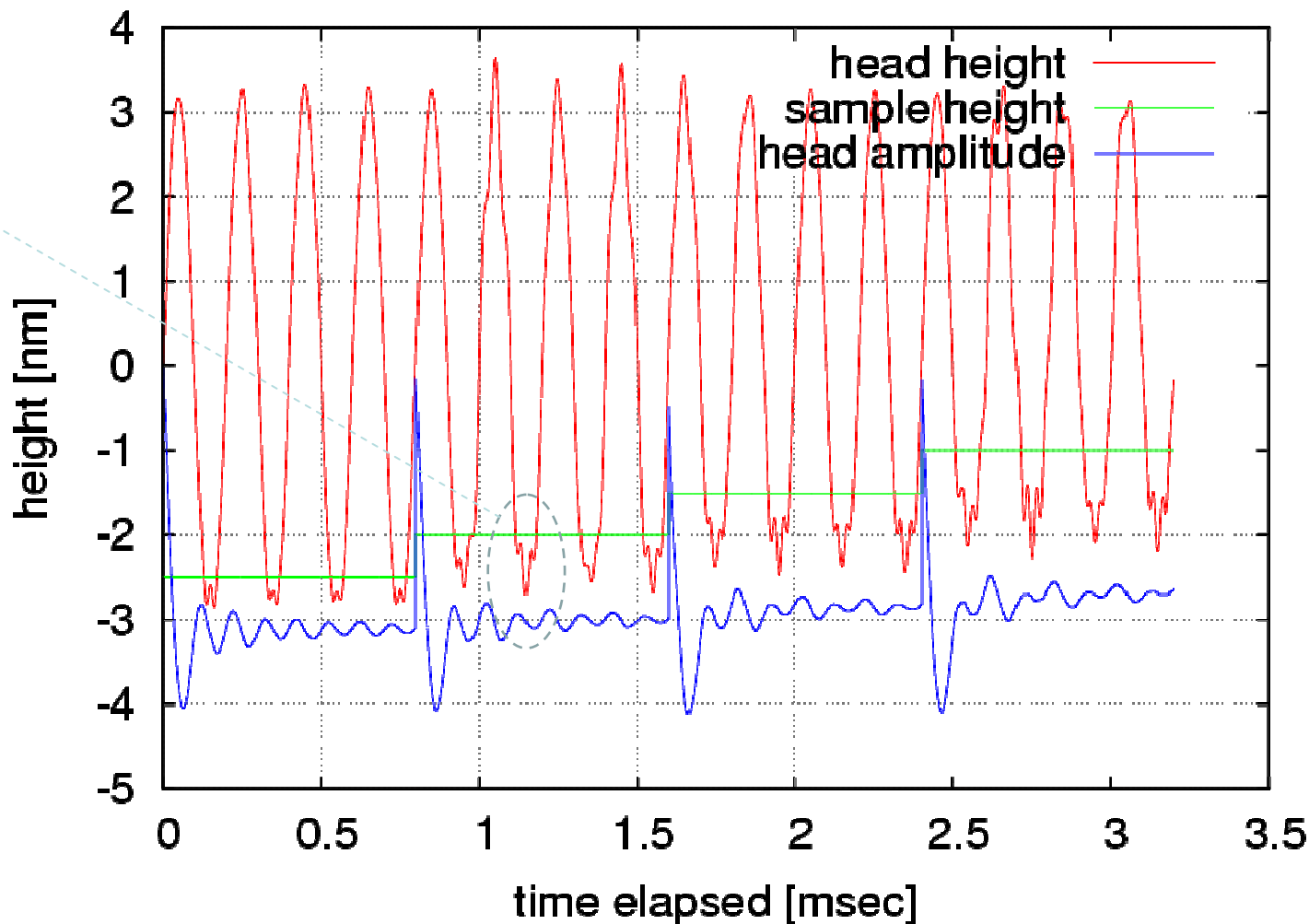


探針から受ける力の影響 1

-ステップ列上の高速スキャンと多重モード-

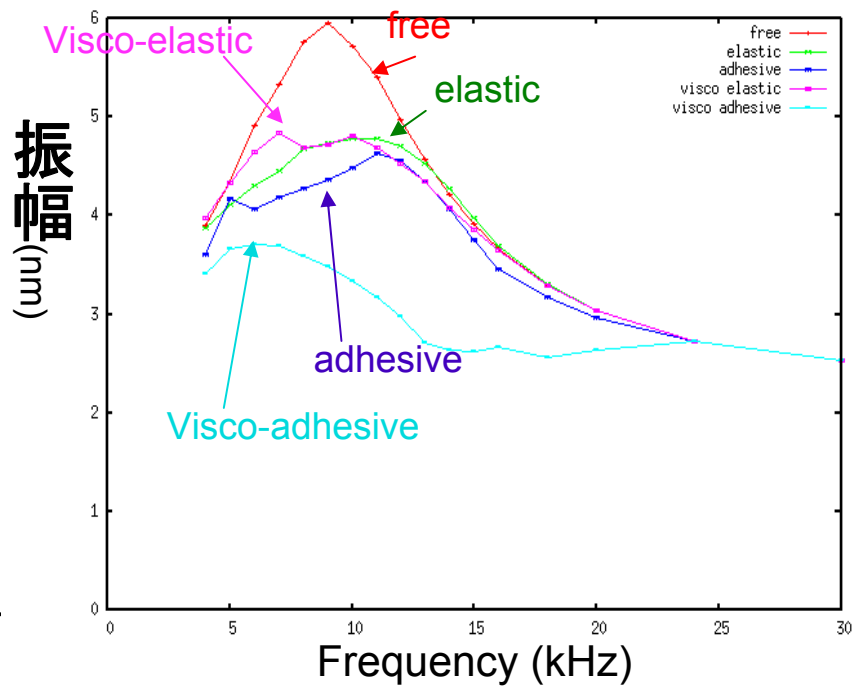
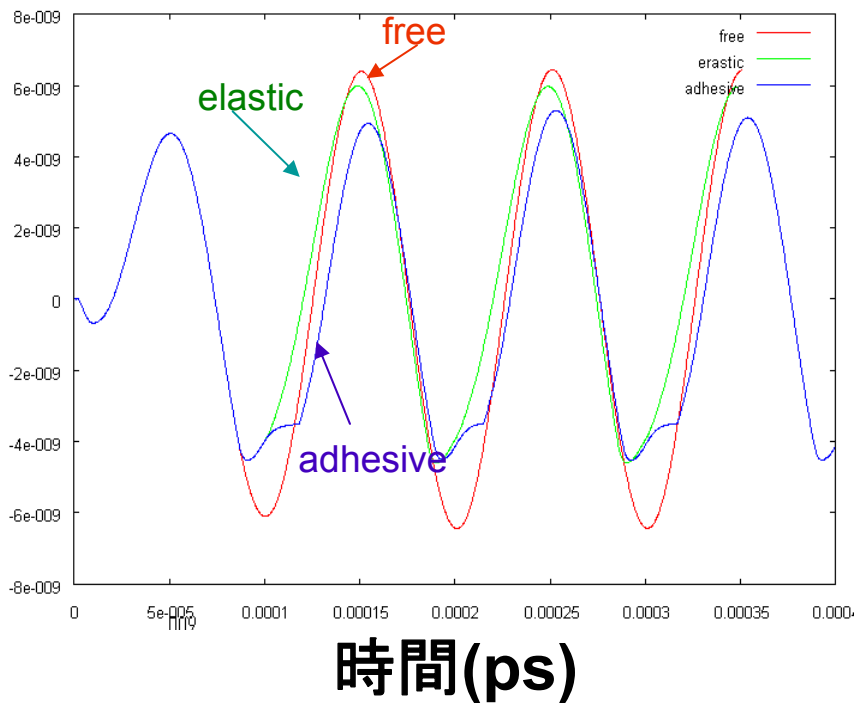


高調波モード
の励起

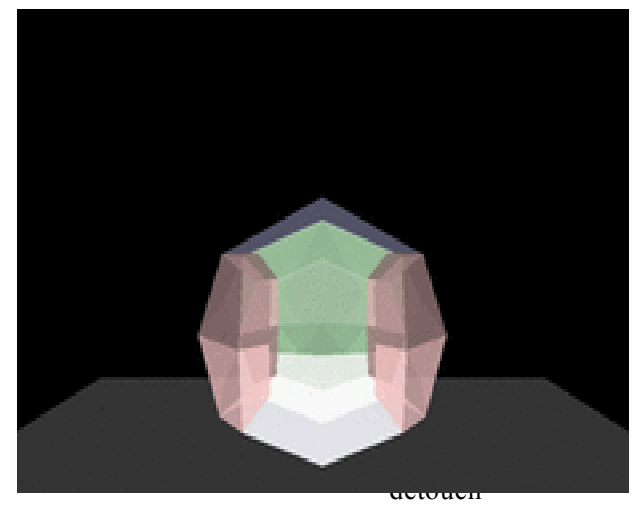
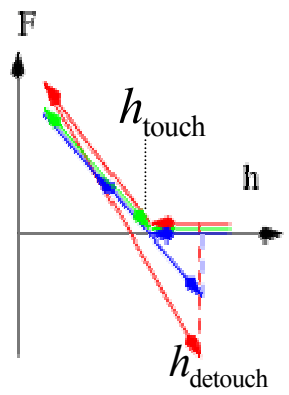


探針の受ける力の影響 2 -水中タッピングモード-

カンチレバー先端



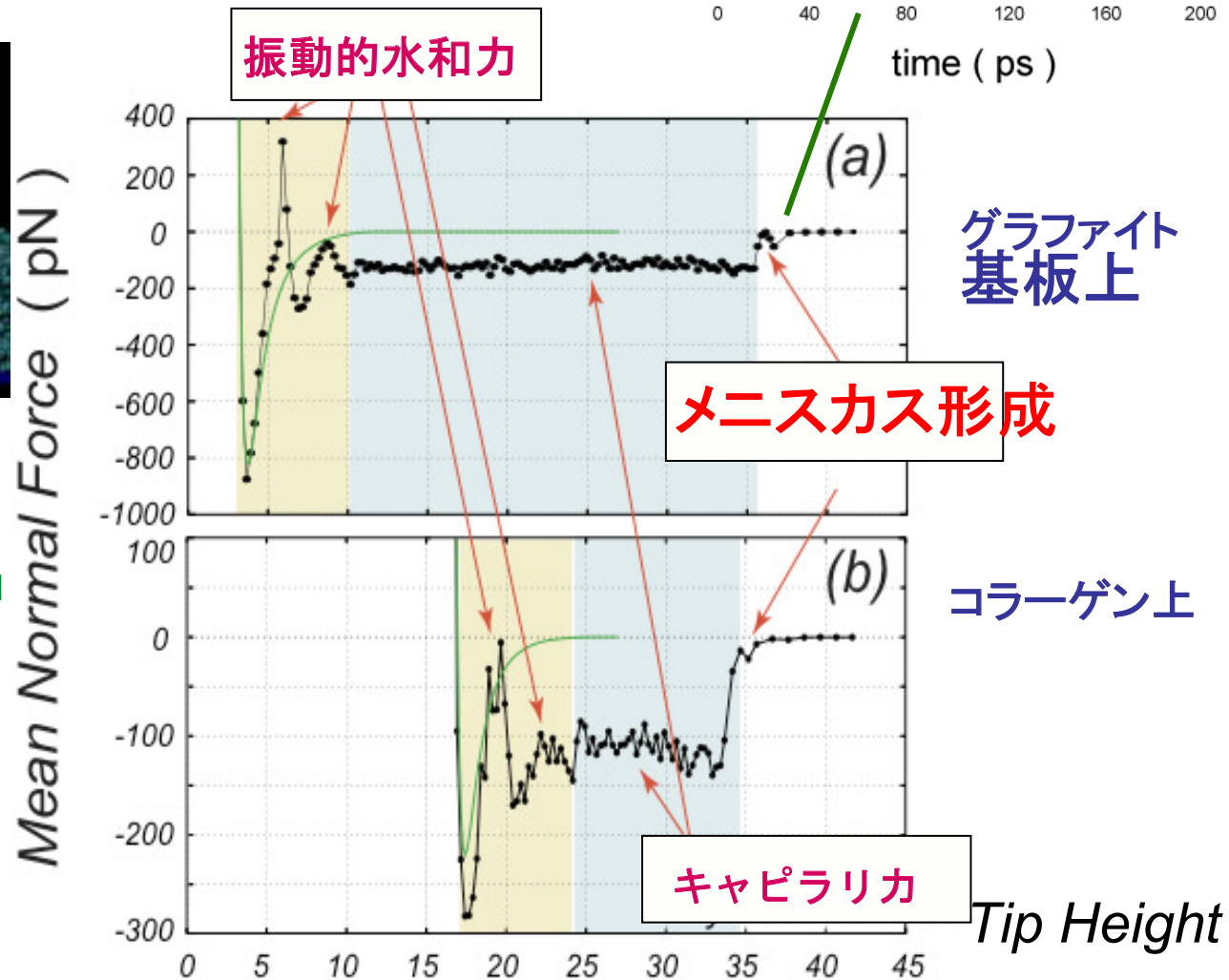
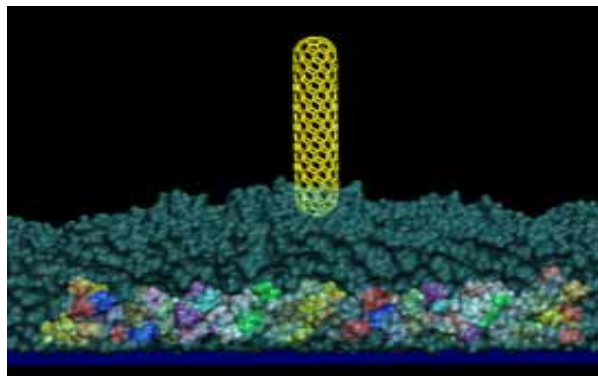
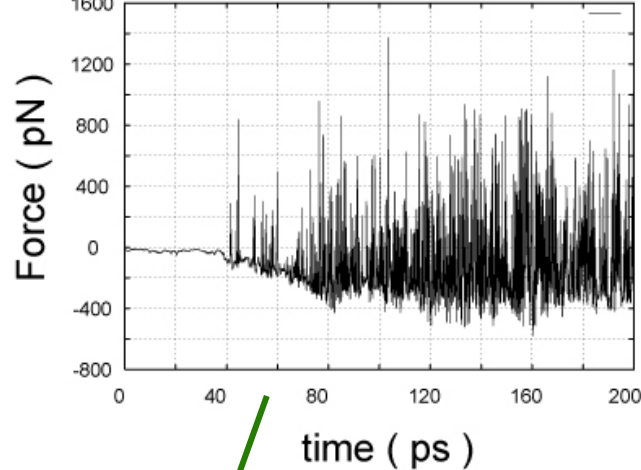
- elastic $f(h) = -k(h - h_{\text{touch}}) \quad h < h_{\text{touch}}$
- adhesive $f(h) = -k(h - h_{\text{touch}}) \quad \begin{cases} h < h_{\text{touch}} \\ h < h_{\text{detach}} \end{cases}$
- Visco-elastic $f(h) = -k(h - h_{\text{touch}}) - \gamma v \quad h < h_{\text{touch}}$
- Visco-adhesive $f(h) = -k(h - h_{\text{touch}}) - \gamma v \quad \begin{cases} h < h_{\text{touch}} & v < 0 \\ h < h_{\text{detach}} & v > 0 \end{cases}$



液体分子に媒介される 探針-試料間相互作用力

水分子に媒介される 探針—試料間相互作用力

古典分子動力学法による AFMシミュレーション ;
水中のCNT 探針とコラーゲン試料



K.Tagami and M.Tsukada,
e-J. Surf.Sci.Nanotech. 4 (2006)311

水中マイカについてのnc-AFM シミュレーション -古典 MD 法

MD 計算条件

マイカ表面サイズ: $36\text{\AA} \times 42\text{\AA}$

探針摸型: (10,0)CNT

水分子ポテンシャル: TIP3P

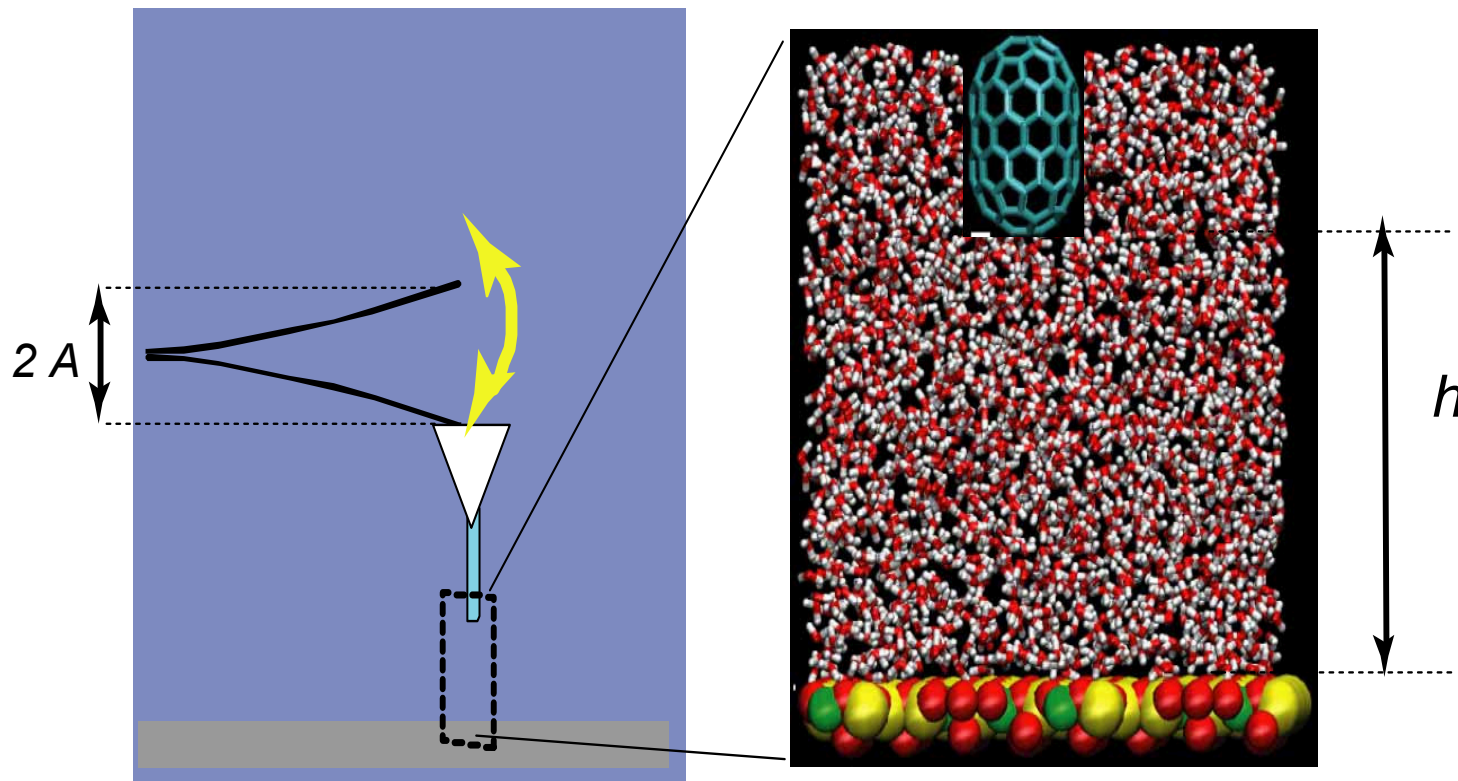
全原子数: 6,338

力場: CHARMM 22 + CLAY (modified)

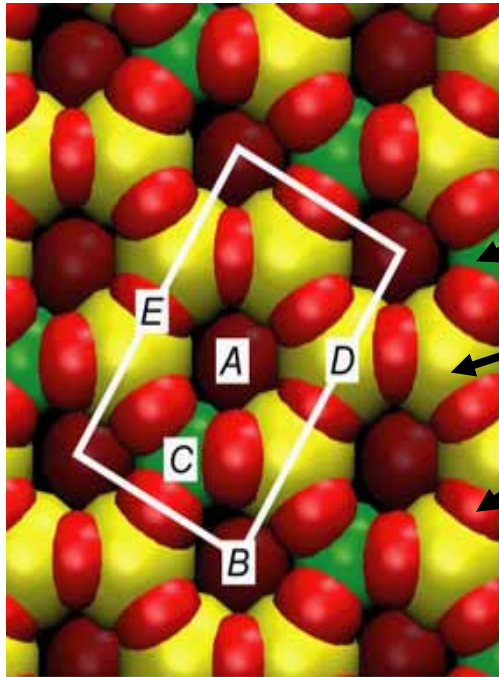
プログラム: NAMD 2.5 and 2.6

温度: 300 K

時間メッシュ: 2fs



Force-distance curve by MD simulation; mica in water by a CNT tip

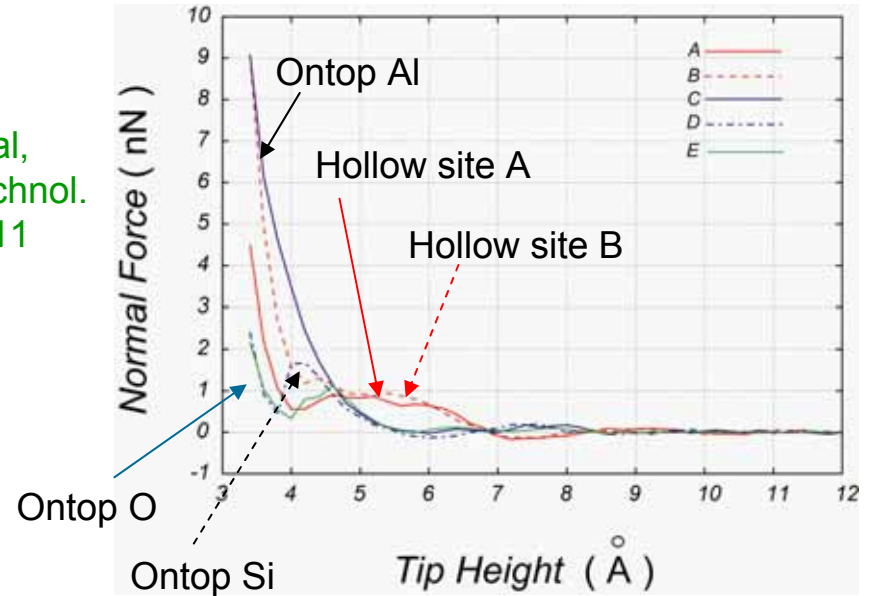


M.Tsukada, et al,
J. Vac. sci., Technol.
B 28, C4C1 2011

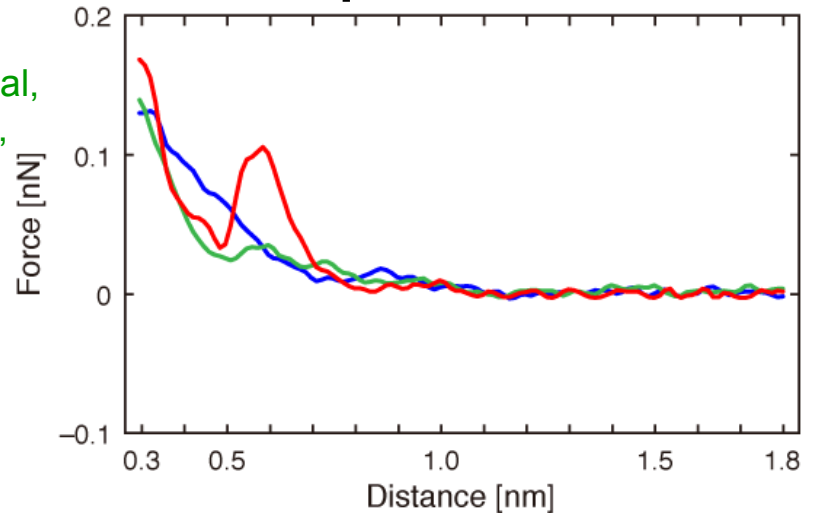
- A, B: ontop of hollow site
- C: ontop of Al atom
- D: ontop of Si atom
- E: ontop of O atom

K.Kobayashi, et al,
Nanotechnology,
submitted

MD simulation



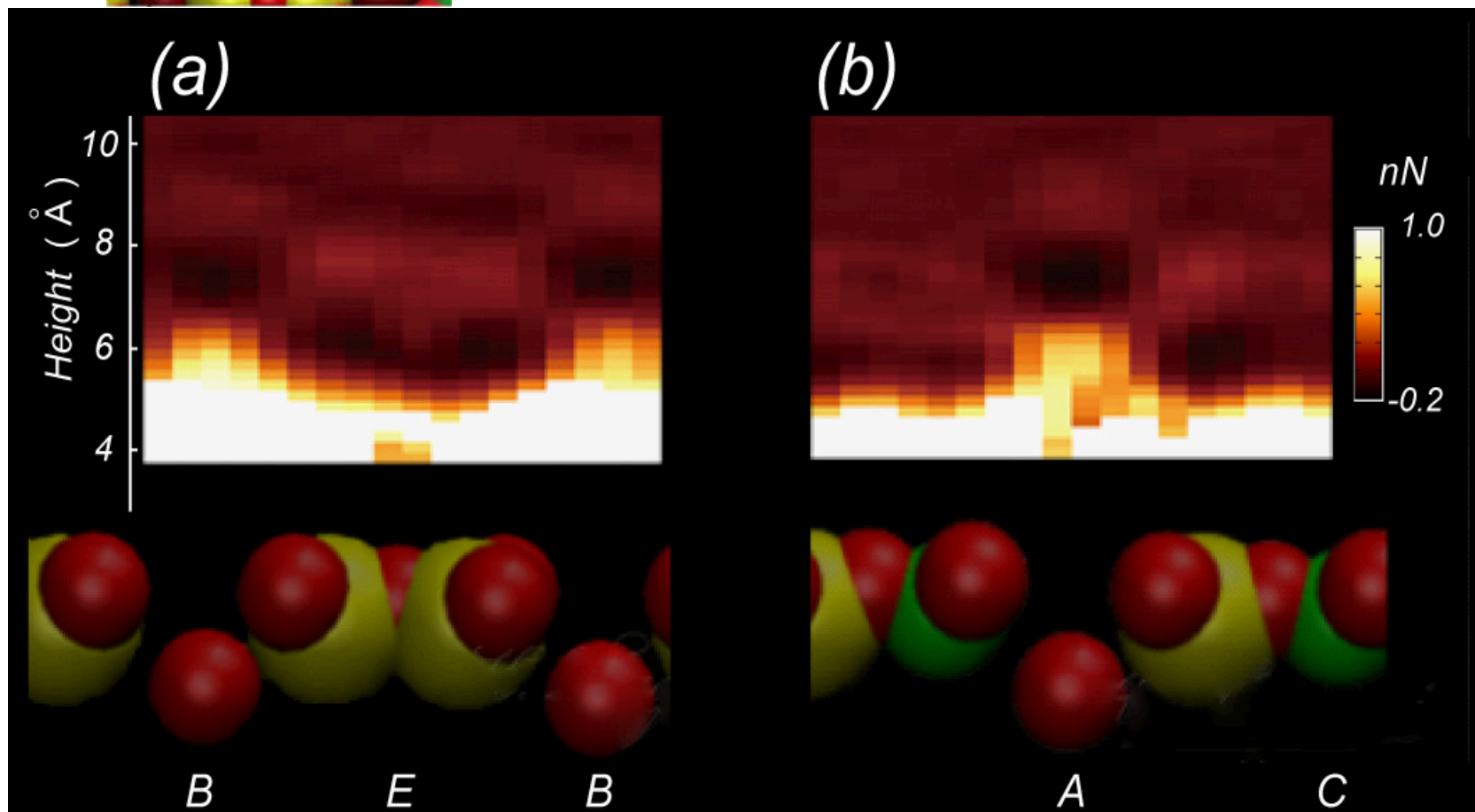
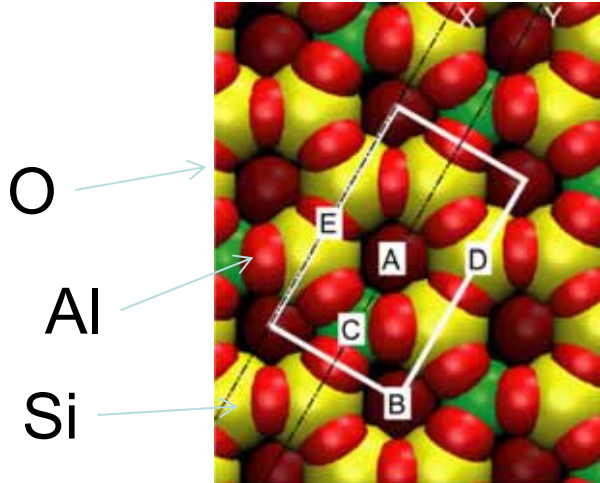
Experiment



水中マイカの 3D力分布の断面像 (SWCNT 探針によるMDシミュレーション結果)

M.Tsukada et al, J. Vac. Sci. B28 (2010) c4c1

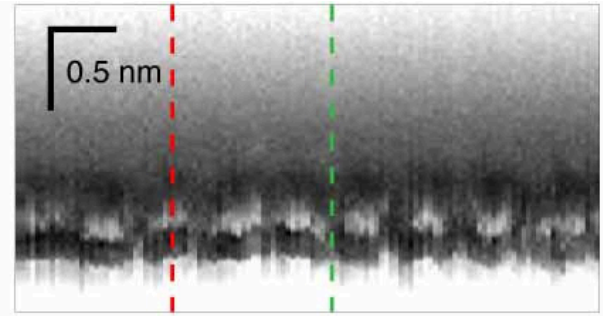
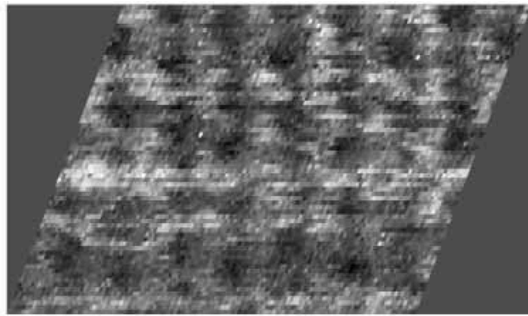
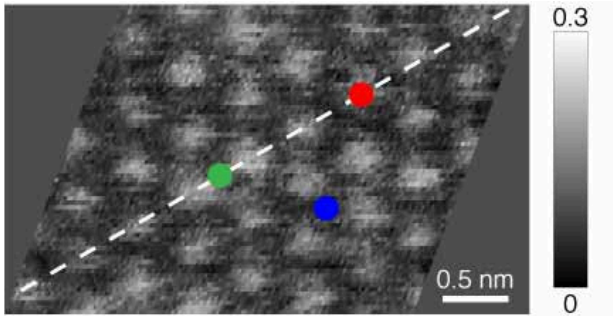
*A, B: ontop of hollow site C: ontop of Al atom
D: ontop of Si atom E: ontop of O atom*



Comparison between the theory and the experiment

Experiment

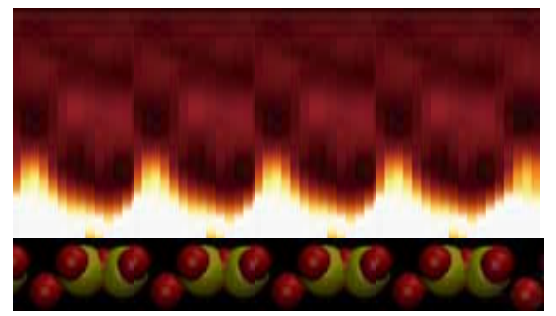
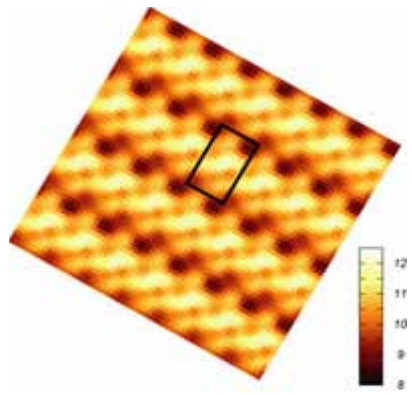
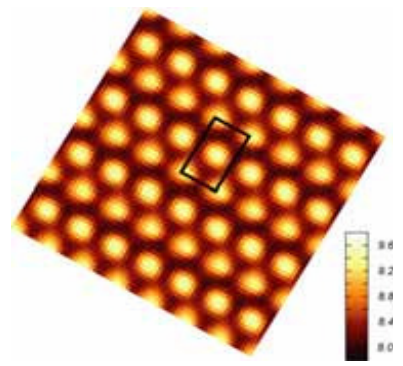
K.Kobayashi, et al, Nanotechnology, submitted



Force map at a horizontal plane with a certain height

Force map at the horizontal plane by 0.2nm closer from the left

Force map at a vertical plane including the dots of the left

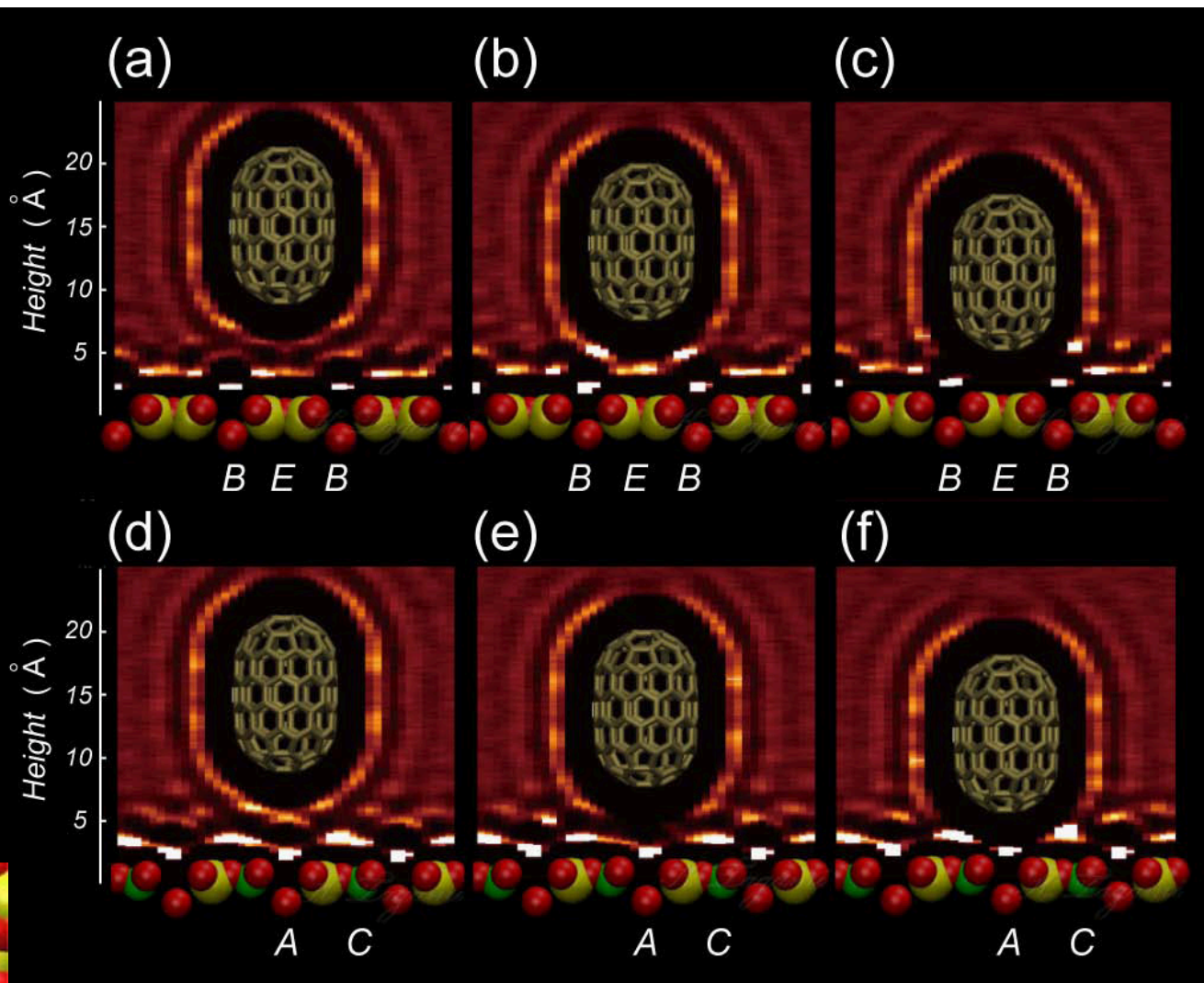
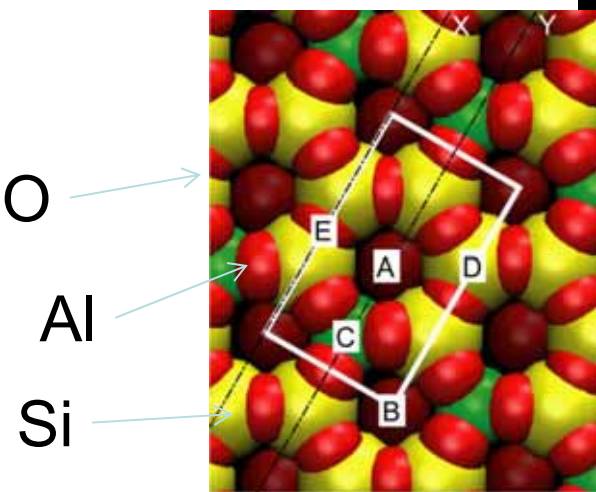


Theoretical Simulation

M.Tsukada et al, J. Vac. Sci. B28 (2010) c4c1

水中マイカと
CNT探針間の
水分子の分布
(O原子)

MDシミュレーション
結果



*A, B: ontop of hollow site C: ontop of Al atom
D: ontop of Si atom E: ontop of O atom*

シミュレーション初期におけるK イオンの挙動

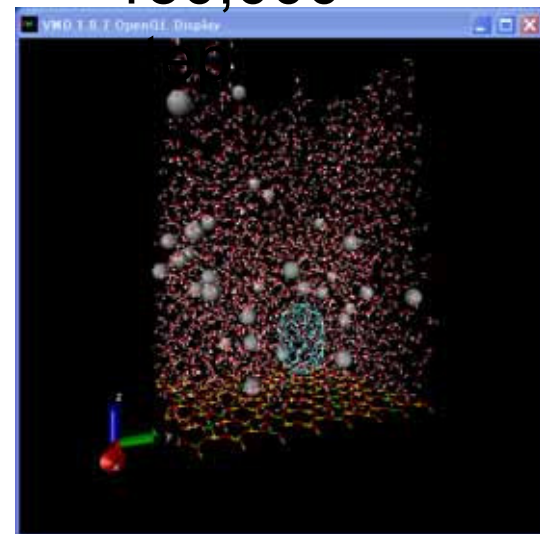
初期構



50,000 step

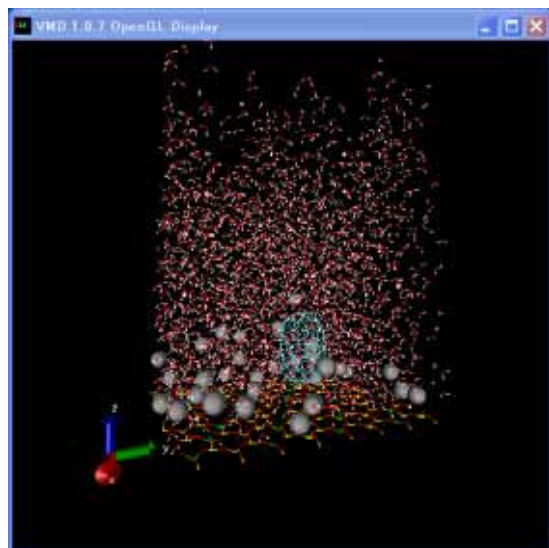


150,000

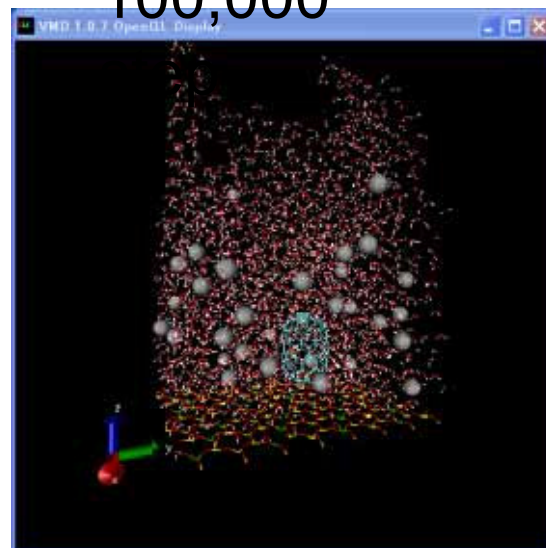


1step=2fs

20,000
step



100,000



水中AFMの力計算のための (3D)-RISM法

$\mathbf{h}, \mathbf{c}, \omega \implies N \times N$ 行列

$N =$ 非等価な原子の数

分子間直接相関関数

$$\omega_{ij}^{\alpha\beta} = \delta_{\alpha\beta} \sin(kl_{ij}) / kl_{ij}$$

分子間全相関関数

分子内原子相関関数

原子分布関数

$$\mathbf{h} = \omega * \mathbf{c} * \omega + \omega * \mathbf{c} * \rho \mathbf{h}$$

convolution

短距離相互作用

長距離相互作用

$$c_{ij} = \exp(-\beta u_{ij}^0 + t_{ij} - \beta \phi_{ij}) - 1 - t_{ij}$$

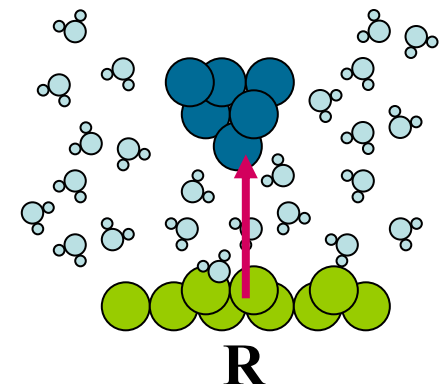
$$\beta = \frac{1}{k_B T}$$

$$\mathbf{t} \equiv \mathbf{h} - \mathbf{c}$$

自由エネルギー

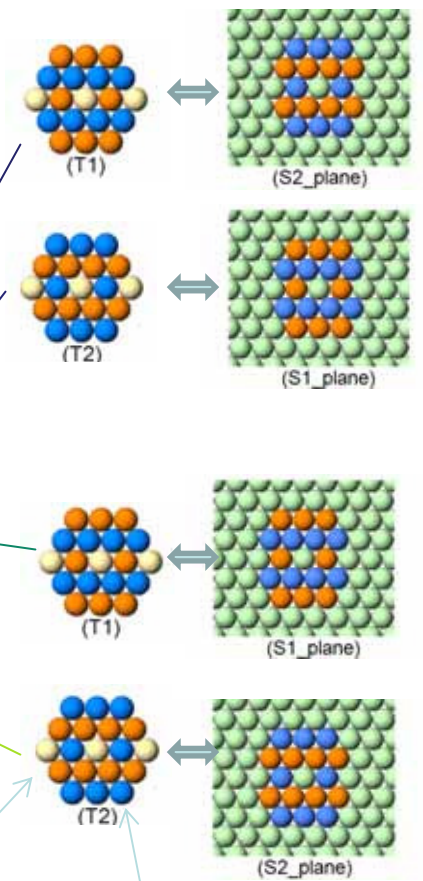
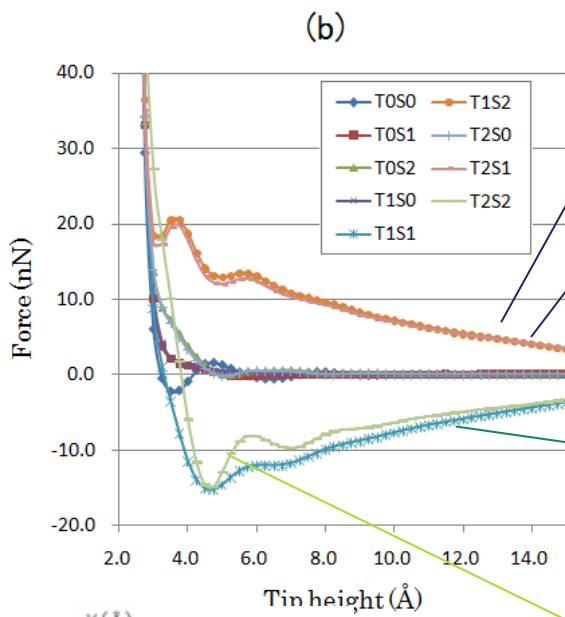
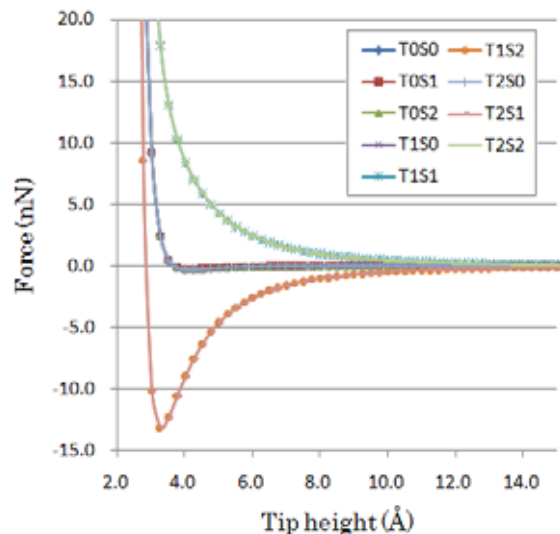
$$W(\mathbf{R}) = \rho k_B T \sum_{ij} \int dr \left\{ \frac{1}{2} [h_{ij}(r)]^2 - c_{ij}(r) - \frac{1}{2} h_{ij}(r) c_{ij}(r) \right\}$$

探針力 $F(\mathbf{R}) = -\frac{\partial W(\mathbf{R})}{\partial \mathbf{R}}$



水中帯電試料の力分布

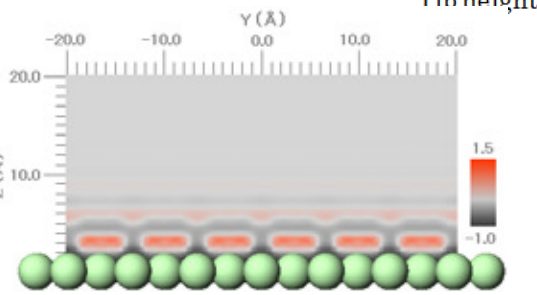
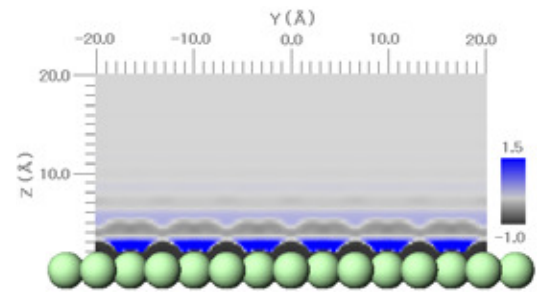
3D-RISM 計算



+0.8e
-0.8e

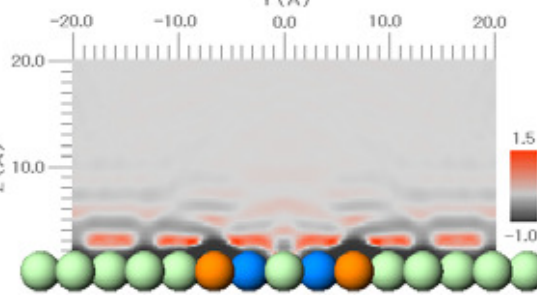
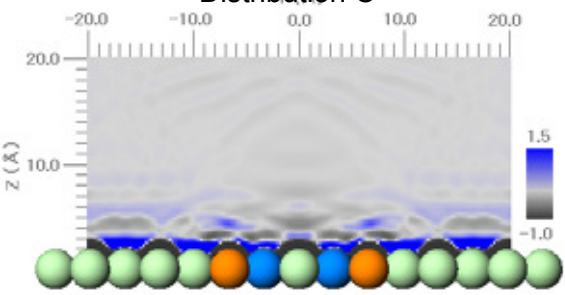
真空中とは異符号の力がより長距離から働く

M.Harada and M.Tsukada,
Phys. Rev. B, 82 (2090) 035414



Distribution O

Distribution H

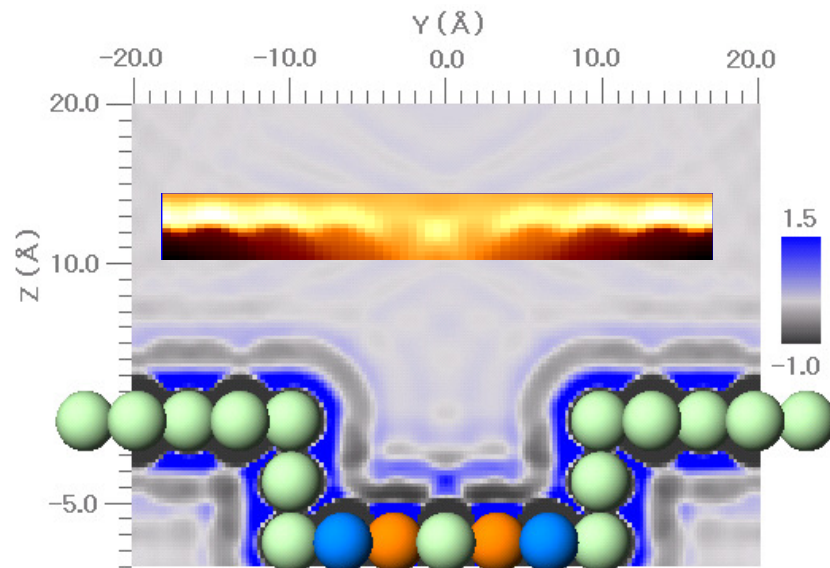
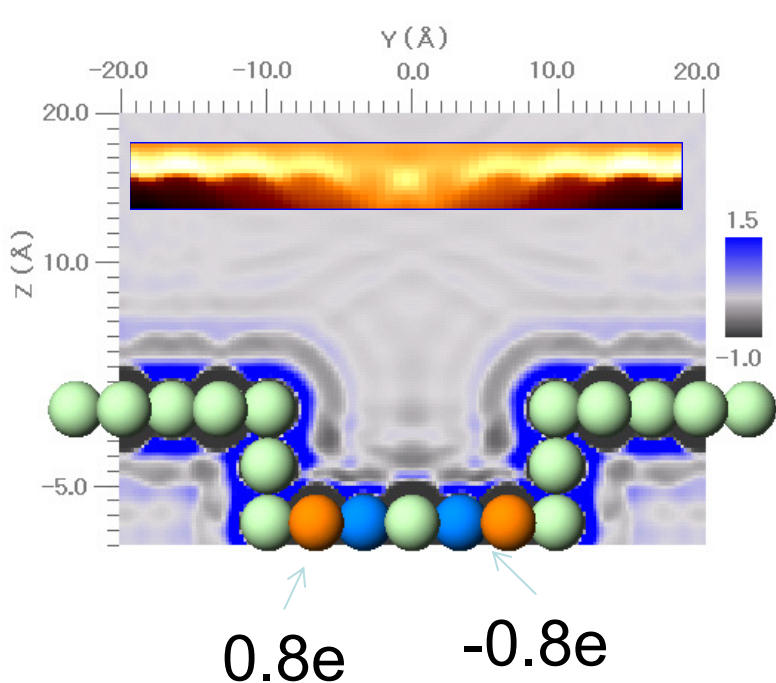
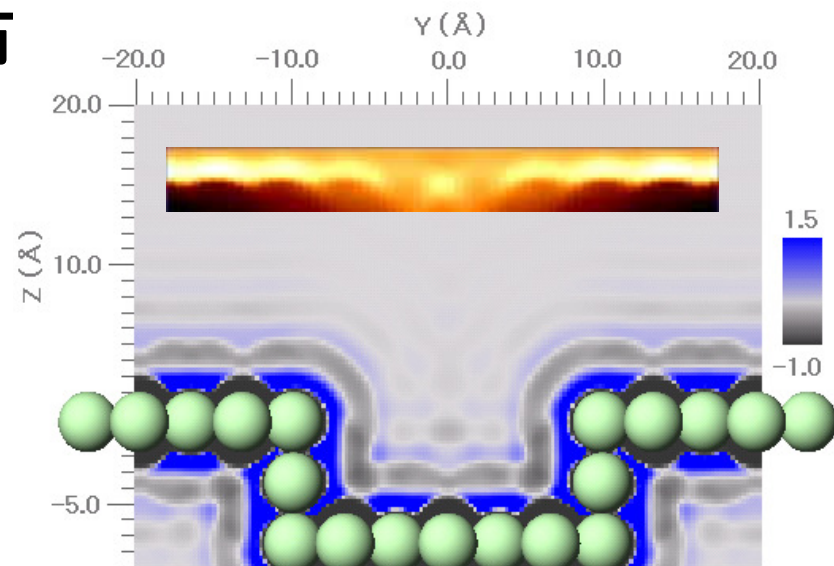
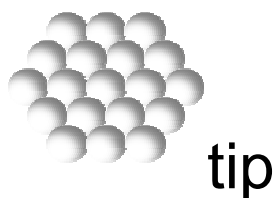


Distribution O

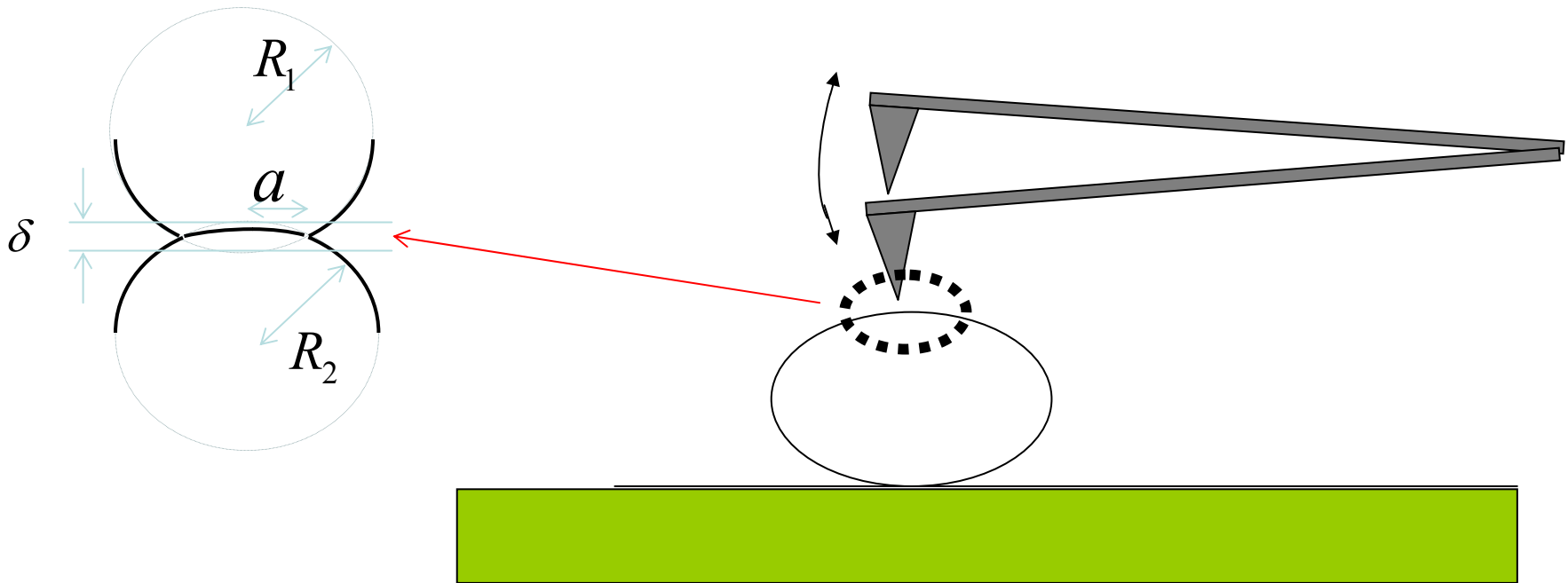
Distribution H

ナノピット周辺の水分子の分布

O分子密度分布
3D-RISM法による計算

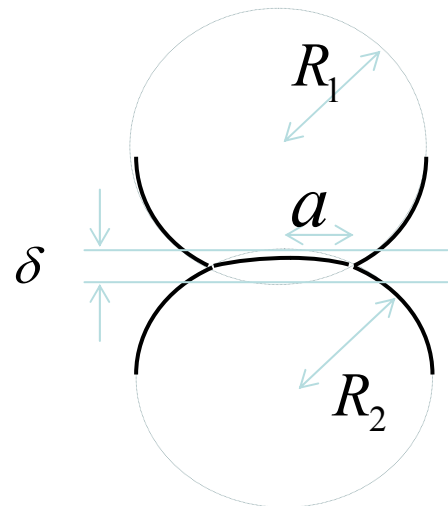


接觸問題



粘弾性試料のAFM計測シミュレーション

接触問題のJKR 理論



力

$$F = \frac{4E^*}{3R} a^3 - \sqrt{16\pi\gamma E^* a^3}$$

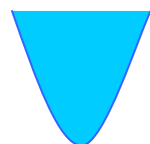
接触半径

実効ヤング率

$$\frac{1}{E^*} = \frac{1-\nu_1^2}{E_1} + \frac{1-\nu_2^2}{E_2}$$

凝着エネルギー

$$U_s = -2\gamma\pi a^2 (= U_{12} - U_1 - U_2)$$



変位

$$\delta = \frac{a^2}{R} \left\{ 1 - \sqrt{\frac{4\pi\gamma R^2}{E^* a^3}} \right\}$$

有効半径

$$\frac{1}{R} = \frac{1}{R_1} + \frac{1}{R_2}$$

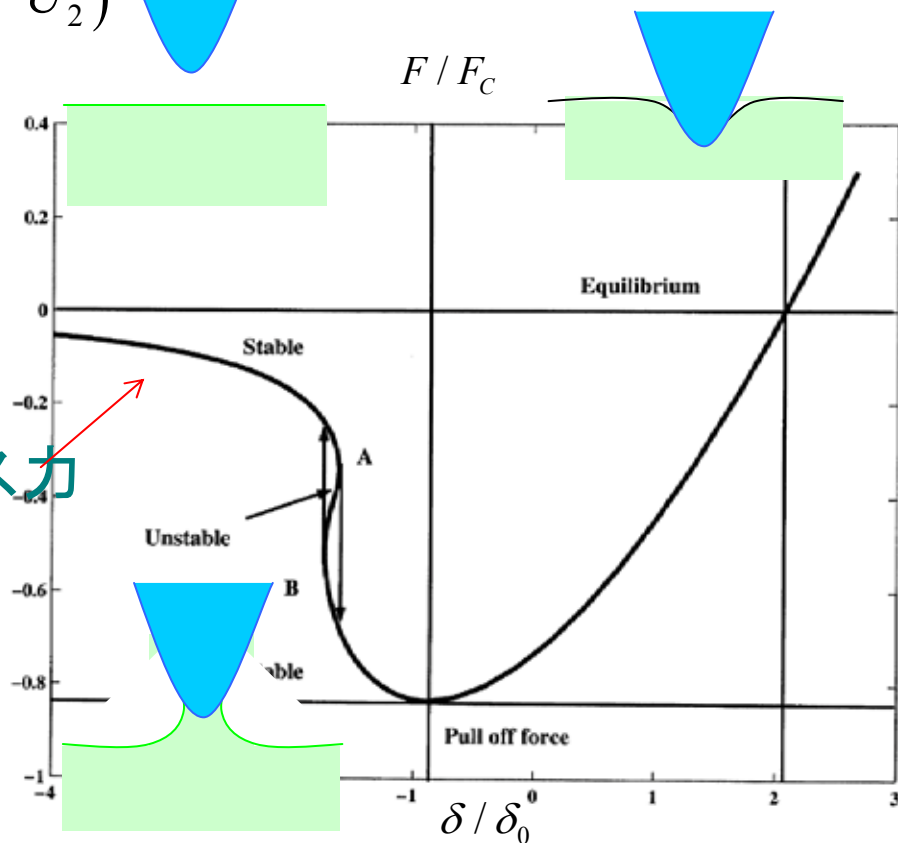
$$a_0 = \left(\frac{9\pi\gamma R^2}{E^*} \right)^{1/3}$$

$$\delta_0 = \frac{a_0^2}{3R}$$

$$F_c = 3\pi\gamma R$$

ファンデアワールス力

$$f_{vdW} = -\frac{A_H R}{6z^2}$$



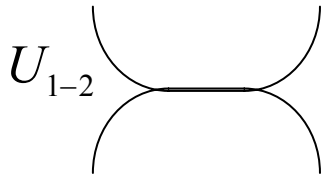
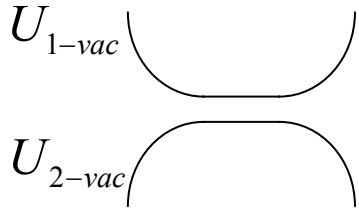
凝着エネルギー: γ

Surface energy for the detached state

$$U_{ditach} = U_{1-vac} + U_{2-vac}$$

Surface energy for the attached state

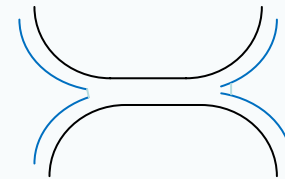
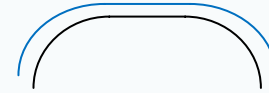
$$U_{tach} = U_{1-2}$$



Adhesion energy

$$\begin{aligned} U_{adhesion} &= U_{ditach} - U_{tach} \\ &= U_{1-vac} + U_{2-detach} - U_{1-2} \end{aligned}$$

For the case of wetting



$$\begin{aligned} U_{adhesion} &= 2A \times u_{water_surf_tension} - A \times u_{water_surf_tension} \\ &= A \times u_{water_surf_tension} \end{aligned}$$

ソフトマテリアルの粘弾性的性質

西一中嶋 による高分子表面の計測

D.Wang et al, *Macromolecules*,
(2010) 43, 3169

理論シミュレーションの方法

$$\rho S(z) \frac{\partial^2}{\partial t^2} h(z) = - \frac{\partial^2}{\partial z^2} EI(z) \frac{\partial^2}{\partial z^2} h(z)$$

$$- \eta(z) \frac{\partial}{\partial t} h(z) + F^{\text{liq}}(z) - \frac{\partial}{\partial z} V_{\text{TS}}$$

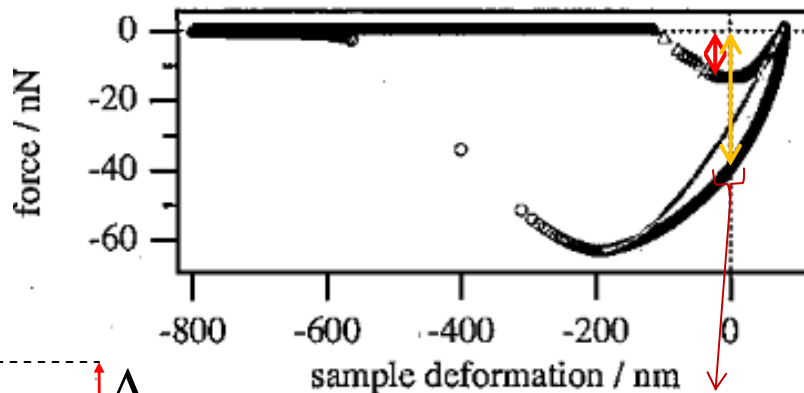
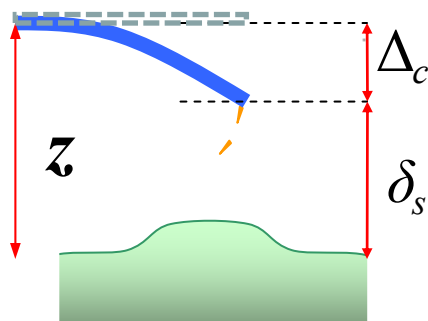
Si_Cantilever: $400\mu\text{m} \times 40\mu\text{m} \times 0.4\mu\text{m}$

$R = 20\text{nm}$ $\nu = 0.01\text{kHz}$ amplitude: 200nm

Sample(tip) Young Modulus:

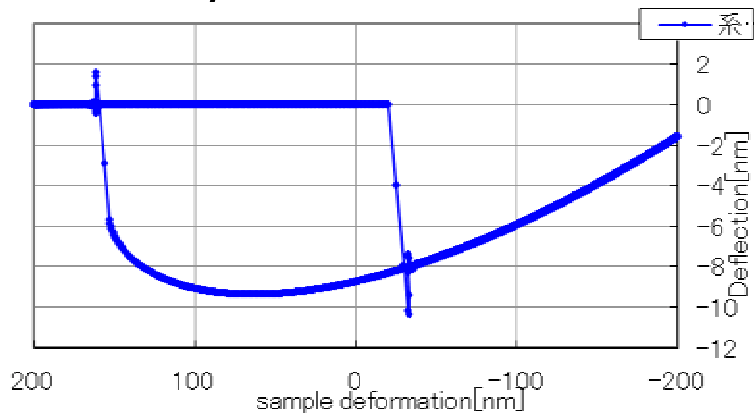
60.0MPa (130GPa)

adhesive_energy(γ) = 10J/m^2

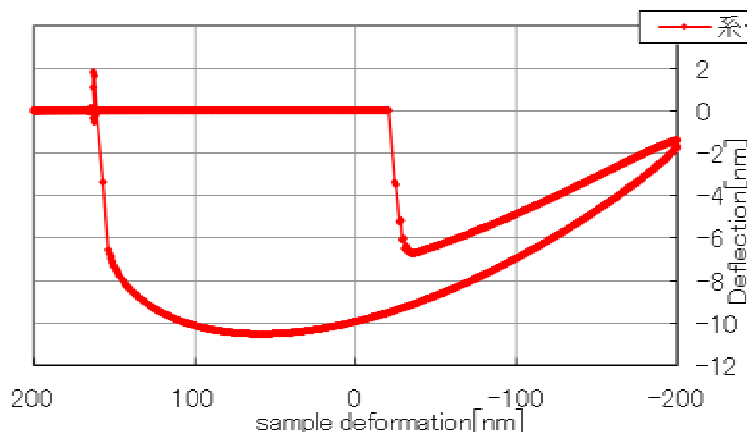


Visco-elastic effect?

$\eta = 0.00$



$\eta = 0.02$



研究協力者

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Advanced Algorithm & Systems
Advanced Algorithm & Systems
Advanced Algorithm & Systems
Advanced Algorithm & Systems



科学技術振興機構研究成果展開事業
【先端計測分析技術・機器開発】
「走査プローブ顕微鏡シミュレータ」

